

# Forecast indices from ground-based microwave radiometer for operational meteorology

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## Abstract

Today, commercial microwave radiometers profilers (MWRP) are robust and unattended instruments providing real time accurate atmospheric observations at ~1 min temporal resolution under nearly all-weather conditions. Common commercial units operate in the 20-60 GHz frequency range and are able to retrieve profiles of temperature, vapour density, and relative humidity. Temperature and humidity profiles retrieved from MWRP data are used here to feed tools developed for processing radiosonde observations to obtain values of forecast indices (FI) commonly used in operational meteorology. The FI considered here include K-index, Total Totals, KO index, Showalter index, T1 Gust, Fog Threat, Lifted Index, S Index (STT), Jefferson Index, MDPI, Thompson Index, TQ Index, and CAPE. Values of FI computed from radiosonde and MWRP-retrieved temperature and humidity profiles are compared in order to quantitatively demonstrate the level of agreement and the value of continuous FI updates. This analysis is repeated for two sites at midlatitude, the first one located at low altitude in Central Europe (Lindenberg, Germany), while the second one located at high altitude in North America (Whistler, Canada). It is demonstrated that FI computed from MWRP well correlate with those computed from radiosondes, with the

1 additional advantage of nearly continuous update. The accuracy of MWRP-derived FI is  
2 tested against radiosondes, taken as a reference, showing different performances depending  
3 upon index and environmental situation. Overall, FI computed from MWRP retrievals agree  
4 well with radiosonde values, with correlation coefficients usually above 0.8 (with few  
5 exceptions). We conclude that MWRP retrievals can be used to produce meaningful FI, with  
6 the advantage (with respect to radiosondes) of nearly continuous update.

7

## 8 **1 Introduction**

9 Commercial microwave radiometers profilers (MWRP) are robust instruments performing  
10 continuous unattended operations and real time atmospheric observations at ~1 min temporal  
11 resolution under nearly all-weather conditions. MWRP perform measurement of thermal  
12 emission from downwelling brightness temperature (T<sub>b</sub>) in the atmosphere. Most common  
13 commercial units operate in the 20-60 GHz frequency (0.5 to 1.5 cm wavelength) range, in  
14 which atmospheric thermal emission is influenced by atmospheric temperature, humidity and  
15 the presence of hydrometeors. From calibrated MWRP T<sub>b</sub>, atmospheric thermodynamic  
16 profiles can be retrieved using a variety of inversion methods, as multivariate regression,  
17 neural networks, and variational approaches (Solheim et al., 1998; Ware et al., 2003; Löhnert  
18 et al., 2004; Cimini et al., 2006, Cimini et al., 2010) with an accuracy that is compatible with  
19 most of meteorology applications, especially in the lower troposphere (Güldner and  
20 Spänkuch, 2001; Hewison, 2007; Cimini et al., 2011; Ware et al., 2013). Due to the increasing  
21 distribution, networks of MWRP are being established for climate and meteorology  
22 applications (Cadeddu et al., 2013; Cimini et al., 2014).

23 Currently operational radiosonde launches are normally performed twice daily by National  
24 and/or regional Weather Services (NWS) at hundreds of sites world wide. Relatively few sites  
25 perform launches four times a day. Radiosondes are usually launched at synoptic hours (00-12  
26 or 00-06-12-18 UTC) and the observed thermodynamic profiles are assimilated into  
27 Numerical Weather Prediction (NWP) model analysis. In addition, the same radiosonde  
28 observations are processed locally at NWS to compute forecast indices (FI) developed starting  
29 from some 60 years ago (Showalter, 1947; Fawbush and Miller, 1954; Galway, 1956; George,  
30 1960) which are still broadly used for operational meteorology and local short-term forecast  
31 (Andersson et al., 1989; Haklander and Van Delden, 2003; Holtslag et al., 2010). Although  
32 the FI based on sounding observations are rather simple, they perform reasonably well,

1 especially once optimized for site specific conditions, and show forecast skills that often  
2 outperform the skill of modern numerical weather prediction models (Kuhlman, 2006;  
3 Holtslag et al., 2010). However, these FI are available at NWS radiosonde sites at the time of  
4 radiosonde flight, i.e. usually two to four times a day. More recently, FI at higher temporal  
5 resolution (~15 min) became available from geostationary satellite retrievals (König 2002;  
6 König and de Coning, 2009; de Coning et al., 2010). Though they are limited to clear sky  
7 conditions, satellite-based FI offer the advantage to cover large areas (at continental scale).  
8 On the other hand, satellite-based FI suffer from the lack of quality data in the boundary layer  
9 due to the low vertical resolution of satellite observations in the lower troposphere.

10 The U.S. National Research Council (NRC) recently reported that continuous boundary layer  
11 temperature, humidity, and wind observations provide a practical and cost-effective means to  
12 improve local high-impact weather forecasting (NRC 2008; 2010). In fact, the structure and  
13 variability of the lower troposphere is currently not well known because vertical profiles of  
14 water vapor, temperature, and winds are not systematically observed with sufficient spatial or  
15 temporal resolution. This lack of observations results in the planetary boundary layer being  
16 the single most important under-sampled part of the atmosphere. Consequently, short-term  
17 forecast skill may be poor due to a lack of pertinent data, particularly in the lower troposphere  
18 where severe weather originates.

19 Conversely, traditional FI developed for radiosondes can be generated from MWRP retrievals  
20 continuously and under nearly all weather conditions. Temperature and humidity profiles are  
21 available from MWRP data at ~ 1 min resolution. Note that most of the information content  
22 resides within the planetary boundary layer (Cimini et al., 2011; 2013) and that useful  
23 information is provided even under precipitation (Cimini et al., 2011; Xu et al, 2014). The  
24 high-temporal resolution MWRP retrievals have recently been exploited in support of  
25 nowcasting low-level windshear at Hong Kong airport (Chan and Lee, 2011), dynamic  
26 weather conditions in US (Knupp et al., 2009), and intense convective weather in Hong Kong  
27 (Chan and Hon, 2011) and South-east India (Madhulatha et al., 2013; Venkat Ratnam et al.,  
28 2013). A similar approach is reported by Feltz and Mecikalski (2002), though using a ground-  
29 based infrared interferometer. In addition, MWRP has been used together with LIDAR to  
30 measure wind and temperature for wind energy applications (Friedrich et al., 2012), revealing  
31 the same accuracy as tower measurements, with the advantage of monitoring stability and  
32 turbulence.

1 Thus, the MWRP-retrieved profiles can be used to feed tools for computing FI developed for  
2 radiosondes profiles, providing timely and continuous FI data. These timely FI data are  
3 particularly important for thunderstorm forecast in the 0- to 6-hour range, as recently shown  
4 for two tropical sites (Chan, 2009; Chan and Hon, 2011; Madhulatha et al., 2013; Venkat  
5 Ratnam et al., 2013). In this paper we extend the application to two sites at midlatitude and to  
6 few additional FI, demonstrating the ability of MWRP retrievals to provide quality FI similar  
7 to radiosonde, as well as the added value of continuous FI data.

8 This paper is organized as follows: Section 2 describes the data set under consideration,  
9 Section 3 summarizes the methodology used for data intercomparison, Section 4 reports the  
10 results of the data analysis. Section 5 summarises the results and draws final conclusions,  
11 suggesting possibilities for additional advancements and application of MWVR observations.

12

## 13 **2 Data set**

### 14 **2.1 Radiosonde data**

15 The radiosondes used in this analysis are Global Position System (GPS) enabled RS92-SGP  
16 systems, manufactured by Vaisala, providing vertical profiles of pressure, temperature,  
17 relative humidity, dew point temperature, and wind at 2-s resolution. These data are then used  
18 to calculate the dew-point temperature and the geopotential height according to hydrostatic  
19 equilibrium. Although depending upon sensor type, radiosondes suffer of some error sources,  
20 including daytime solar radiation dry bias, horizontal drift, time lag and calibration errors at low  
21 temperatures. Nevertheless, radiosondes remain the *de facto* standard for upper air monitoring  
22 and presently provide the most widely available information on the vertical structure of the  
23 troposphere and lower stratosphere. For the type used during the experiment, the  
24 specifications for total measurement uncertainty in soundings are 1.0 mb for pressure, 0.5 °C  
25 for temperature, 5% for relative humidity, and 0.2 m/s for wind speed (Vaisala, 2013). Four  
26 radiosondes per day were launched at standard synoptic hours (00, 06, 12, and 18 UTC) from  
27 the two sites considered in this study.

### 28 **2.2 MWRP data**

29 The MWRP data used in this analysis are provided by two MP-3000A units manufactured by  
30 Radiometrics. The MP-3000A units include a scanning multichannel microwave radiometer, a

1 one-channel broad-band infrared (IR) radiometer, and surface pressure, temperature, and  
2 humidity sensors. The MWRP IR radiometer (one channel covering approximately 9.6–11.5  
3  $\mu\text{m}$ ) measures sky IR temperature and gives information on cloud-base temperature. The  
4 MWRP meteorology sensors measure temperature (Ts), pressure (Ps), and relative humidity  
5 (RHs) at the instrument level. The multichannel microwave radiometer can observe Tb at up  
6 to 35 channels in the 20-60 GHz frequency (0.5 to 1.5 cm wavelength). In this frequency  
7 range, atmospheric thermal emission comes from atmospheric gases (primarily oxygen and  
8 water vapour) and hydrometeors (mainly liquid water particles, since ice emission is  
9 negligible). The Rayleigh scattering regime applies up to sizes of small raindrops and in  
10 general the scattering contribution is negligible up to light precipitation.

11 When properly calibrated, a MWRP provides Tb with an absolute accuracy of  $\sim 0.3\text{--}0.7$  K  
12 (Cimini et al. 2003; Löhnert and Maier, 2012; Maschwitz et al., 2013). Atmospheric  
13 temperature and humidity profiles can be retrieved from MWRP Tb with a variety of  
14 inversion methods, including multivariate regression, neural networks, and variational  
15 approaches (Solheim et al., 1998; Löhnert et al., 2004; Hewison, 2007; Cimini et al., 2006;  
16 2010). Typical root-mean-square accuracy for tropospheric temperature and absolute  
17 humidity profiles during non-precipitating conditions are respectively  $\sim 0.5\text{--}2.0$  K and  $0.2\text{--}1.5$   
18  $\text{g/m}^3$  (Göldner and Spänkuch, 2001; Cimini et al., 2011). Accuracy estimates during  
19 precipitation including heavy rain have been reported as equal to 3.1 K and  $1.9 \text{ g/m}^3$  (Xu et al,  
20 2014).

21 For the data set used in this analysis, the MWRP observed Tb at 22 channels and at 2  
22 elevation angles (zenith and  $15^\circ$  elevation) and one fixed azimuth angle. The microwave  
23 radiometer is calibrated using noise diode injection to measure the system gain continuously.  
24 The noise diode effective temperature is determined by observing an external cryogenic target  
25 less frequently (once every three to six months). The main characteristics of the MWRP  
26 microwave radiometer are reported in Table 1.

27

## 28 **3 Methodology**

### 29 **3.1 MWRP retrieval techniques**

30 Atmospheric temperature and humidity profiles are retrieved from MWRP observations using  
31 any of the above mentioned inversion methods. The MP-3000A proprietary algorithm deploys

1 a neural networks (NN) method (Solheim et al., 1998), trained with thousands of profiles  
2 generated from historical data sets of operational radiosondes. The proprietary software offers  
3 two versions of the NN retrievals, which may run separately and in parallel, one ingesting  
4 zenith observations (NNz) and the other ingesting the available slant observations (NNa).  
5 Alternatively, other methods can be applied to retrieve temperature and humidity profiles  
6 from MP-3000A data, as multivariate regression or variational approaches. Observation-based  
7 multivariate regression (ObsREG), using MWRP and radiosonde measurements from the past  
8 to calculate regression operators, has been successfully demonstrated to remove systematic  
9 errors and produce weak-biased retrievals with respect to radiosondes (Güldner and  
10 Spänkuch, 2001; Cimini et al., 2006). More recently, the use of a one-dimensional variational  
11 (1-DVAR) technique, coupling radiometric observations with outputs from a numerical  
12 weather prediction (NWP) model, has been demonstrated (Cimini et al., 2006; Hewison,  
13 2007; Cimini et al., 2009; Cimini et al., 2011). The 1-DVAR method combines observed and  
14 forward-modelled Tb with measurement and background error covariance matrices to  
15 optimize retrieval accuracy with respect to observation and model uncertainties. The accuracy  
16 of temperature and humidity profile retrievals in the boundary layer and lower troposphere  
17 depends primarily on the MWRP observations, while in the upper troposphere depends  
18 primarily on the NWP model output. Thus, the 1-DVAR approach avoids the error inherent in  
19 methods initialized with local climatology and benefits from recent surface, radiosonde,  
20 satellite, radar, and other data assimilated in the local NWP analysis and forecast.

21 Figure 1 shows the statistical results for water vapour and temperature profiles computed  
22 using the above methods as compared with radiosondes profiles. In Fig. 1 are reported the  
23 mean difference (MD), standard deviation (STD), and root-mean-square (RMS) difference for  
24 simultaneous profiles (from ObsREG, NNa, NNz, and 1-DVAR), using radiosonde as the  
25 reference. These results are obtained in the period May-June 2010 for a continental site at  
26 midlatitude, the Richard-Aßmann-Observatorium in Lindenberg, Germany, belonging to the  
27 German Weather Service (Deutscher Wetterdienst, DWD). Figure 1 shows the results from  
28 the 233 cases in which all the data sources (radiosondes and MWRP) are simultaneously  
29 available. All observations during all weather conditions are included in the statistical  
30 comparison. Concerning temperature profiles, Fig. 1 suggests that both ObsREG and 1-  
31 DVAR show a small bias (MD within 1 K) relatively to NNa and NNz (MD within 3 and 6 K,  
32 respectively for NNz and NNa). Although the methods show similar STD in the boundary  
33 layer, this tends to separate for altitudes higher than 1 km: STD remains within 1 K up to 10

1 km for 1-DVAR, while it increases with height for ObsREG, NNz and specially NNa. The resulting RMS remains within 1 K up to 10 km for 1-DVAR, within 2 K for ObsREG and 3 K for NNz, while it exceeds 6 K between 2.5-4 Km for NNa. Fig. 1 confirms that 1-DVAR outperforms the other considered methods for temperature profiling, minimising both the systematic and random errors by benefiting from recent data assimilated in the NWP model. Concerning humidity profiles, Fig. 1 reports similar performances for the four techniques, though ObsREG and 1-DVAR show smaller bias in the 2-4 Km range and 1-DVAR shows degraded performances in the lowest 1 km layer. Similar results were obtained for other environmental conditions (Cimini et al., 2011; Ware et al., 2013), specifically for the mountain site in Whistler, Canada, which will be introduced in Section 4.

11

## 12 **3.2 Forecast Indices**

13 Forecast indices are used at various airports and NWS as tools for operational meteorology, e.g. to provide a quantitative and objective way to assist forecasters in issuing weather hazard alerts (Haklander and Van Delden, 2003). There are a number of FI that have been developed and are currently used, depending upon the particular climatology of various sites. A quite comprehensive review can be obtained from Miller (1972), Peppier (1998), and Haklander and Van Delden (2003). FI are usually computed from radiosonde profiles of temperature, humidity, and wind (if available). When only temperature and humidity profiles are available, a reduced set of FI can be computed. This is the case for PTU (pressure, temperature, relative humidity) radiosondes, which are not equipped for wind estimation, as well as for MWRP. Therefore, temperature and humidity profiles retrieved by MWRP may be given in input to forecast tools developed for computing FI from PTU radiosondes. FI from temperature and humidity profiles are also estimated from geostationary satellites retrievals (König 2002; König and de Coning, 2009; de Coning et al., 2010). These satellite FI estimates are produced operationally and cover most of the Earth surface at some 3-10 km resolution. However, satellite FI are based on infrared sounding channels, which tend to saturate in presence of clouds, and thus are only available in clear sky conditions. Moreover, the reliability of satellite FI is hampered by the rather coarse vertical resolution of temperature and humidity profile retrievals from geostationary satellites, particularly in the lower troposphere.

1 More details on the FI considered in this paper are provided in Appendix A. Note that these  
2 simple methods have the advantages that they are based on reproduction of actual  
3 atmospheric processes, which should be broadly applicable while being relatively easy to  
4 understand and implement. The FI values presented in the next Sections were computed by  
5 processing temperature and humidity profiles with the universal RAwinsonde OBservation  
6 (RAOB) program software ([www.raob.com](http://www.raob.com)). FI from radiosondes and MWRP were  
7 computed independently. Note that it is beyond the scope of this paper to demonstrate the use  
8 and the forecast skills of the various FI. This topic is discussed in the review papers  
9 mentioned above (e.g. Haklander and Van Delden (2003)), and it is still object of debate  
10 within the weather forecast community (e.g. Doswell and Schultz, 2006). The aim of this  
11 paper is to investigate the feasibility of producing good quality FI from MWRP observations  
12 and to quantify the agreement and correlation with analogous FI estimated from radiosondes.  
13 If the agreement is deemed satisfactory, we shall conclude that MWRP can deliver additional  
14 valuable products that may complement radiosondes, or even supply for the lack thereof, in  
15 support to operational meteorology.

16

## 17 **4 Results**

18 This Section presents the results of computing FI from MWRP temperature and humidity  
19 profiles and their agreement with the analogous FI computed from radiosonde profiles. The  
20 results are given for two sites corresponding to different environmental conditions. The first  
21 site is in Lindenberg (Germany) at the Meteorological Observatory Lindenberg - Richard-  
22 Assmann-Observatory (MOL-RAO) operated by the German Meteorological Service  
23 (Deutscher Wetterdienst, DWD). Lindenberg is located at midlatitude ( $52.17^\circ$  N,  $14.12^\circ$  E)  
24 and low altitude (98 m above sea level (asl)) in a rather flat rural area in Central Europe. The  
25 second site is in Whistler (Canada) at the meteorological station operated by Environment  
26 Canada – Meteorological Service of Canada – in support of nowcasting and short-term  
27 weather forecasting during the Vancouver 2010 Olympic and Paralympic Winter Games  
28 (Mailhot et al., 2010). Whistler is located at midlatitude ( $50.09^\circ$  N,  $122.98^\circ$  W) and relatively  
29 high elevation (776 m asl) in a mountainous environment along the Pacific Ranges of the  
30 Coast Mountains in western North America.

31 Two 24-hour time series of K-index as computed from radiosonde and MWRP profiles in  
32 Lindenberg are shown in Figure 2. These are typical continental summer-time cases (12 and

1 15 August 2010), in which convection starts to develop after the sunrise, generating  
2 thunderstorms in the afternoon. As explained in Appendix A, the K index is such that the  
3 higher the value, the higher the probability of thunderstorms. In particular, empirical  
4 thresholds are often used to separate weak ( $K\text{-index} < 25$  K) from moderate ( $25 \text{ K} < K\text{-index}$   
5  $< 35$  K) and finally strong thunderstorm potential ( $K\text{-index} > 35$  K). Although it is beyond the  
6 scope of this paper to demonstrate the skills of FI and the applied thresholds, Fig. 2 shows  
7 how increasing values of K-index correspond to increasing instability, eventually culminating  
8 into a thunderstorm. In fact, we see K-index values increasing from below the weak-potential  
9 threshold in the morning to above the high-potential threshold in the afternoon, and then  
10 decaying down in the evening. Multiple thunders were reported nearby Lindenberg in the  
11 afternoon of both days. These time series suggest that the K-index computed from MWRP  
12 profiles follows quite reasonably the trend given by the radiosondes, launched 4 times a day.  
13 Moreover, it can be appreciated the value of the nearly continuous ( $\sim 1$  min resolution) K-  
14 index provided by the MWRP with respect to the information provided by the radiosondes at  
15 a rather coarse time spacing (6 hours). For example, considering the trend of K-index  
16 suggested by the radiosondes between 6 and 18 UTC of 15 August 2010, the thunderstorm  
17 potential seems to be decreasing steadily from nearly strong to weak values. By looking at  
18 radiosonde K-index only, a forecaster would have missed the rapid increase in instability after  
19 12 UTC indicated by the MWRP, which largely overshoot the strong potential and likely  
20 generated the thunderstorm reported right after 16 UTC.

21 For the present analysis, a total of 61 days of MWRP data and 244 radiosonde ascents at 6-h  
22 intervals are used for Lindenberg, while a total of 17 days of MWRP data and 68 radiosonde  
23 ascents at 6-h intervals are available for Whistler. Figure 3 shows the 17-day time series of K-  
24 index in Whistler for the period 12-28 February 2010 (Julian day 43-59). In this period the K-  
25 index computed by radiosondes always reported weak to moderate thunderstorm potential,  
26 which is reasonable for Whistler during winter time. However, the K-index computed from  
27 MWRP retrievals shows a pick exceeding the high-potential threshold on February 16 (Julian  
28 day 47), which was followed by a snow storm (Cimini et al., 2011; Ware et al., 2013). Other  
29 snow storms were experienced during the periods between 12-15 and 24-27 February (Julian  
30 day 43-46 and 55-58), in which the K-index from both radiosondes and MWRP occasionally  
31 exceeds the moderate-potential threshold. Note that the trend of K-index indicated by the  
32 radiosonde is followed better by the 1-DVAR than the NNz retrievals. This is especially  
33 evident during clear sky and fair weather conditions (as for example between Julian day 49-

1 55). In fact, these conditions were associated with decreased moisture at 850-700 mb levels  
2 and increased static stability between 850 and 500 mb, causing extremely low values of K-  
3 index. This is a direct consequence of the situation pictured in Figure 1, which shows lower  
4 systematic and random errors for 1-DVAR than for NNz retrievals in the upper air, where the  
5 850-500 mb pressure levels reside. Note also that during clear nocturnal conditions the MWR  
6 observations were particularly useful to detect a cold bias in the analysis boundary layer  
7 temperature (Ware et al., 2013), which were used as initial condition for 1-DVAR. This  
8 confirmed the large uncertainty associated to gridded analysis in the nocturnal boundary layer  
9 (Hart et al., 1998; Hart and Forbes, 1999).

10 Similarly, Figures 4 and 5 show the time series for the same period but for other forecast  
11 indices, namely the Total Totals, STT, KO, Lifted Index, Showalter Index, Fog Threat, T1  
12 Gust, and finally Jefferson Index. Note that, as detailed in Appendix A, some FI have inverted  
13 trend, i.e. the lower the value, the higher the potential. For Total Totals, KO, Showalter Index,  
14 Lifted Index, STT, and Jefferson Index the same considerations for Figure 3 apply: the trend  
15 indicated by radiosondes is well captured by the MWRP estimates, specially those computed  
16 from 1-DVAR retrievals, both for the diurnal and extra diurnal cycles. More in detail, the  
17 Lifted index and Showalter index closely resemble the behaviour discussed above for the K-  
18 index, while some other FI, namely the Total Totals, KO, STT, and Jefferson Index exceed  
19 the high-potential threshold for all the three periods in which snowstorms happened.

20 For other two of the considered FI, specifically Fog Threat and T1 Gust, MWRP estimates  
21 again follows quite well the trend indicated by radiosondes, but the difference between 1-  
22 DVAR and NNz is difficult to appreciate. The Fog Threat values indicate low potential  
23 throughout the period, except for February 15 (Julian day 46), few hours before a sudden fog  
24 event occurred. However, other few fog/mist events were reported (e.g. Julian days 43, 45,  
25 48, 59), in correspondence of which the Fog Threat shows values from low to moderate  
26 potential. The T1 Gust shows maximum wind gust up to 45 knots (~23 m/s), though reported  
27 winds at the radiosonde launching site did not exceed 20 knots (~10 m/s).

28 In order to make a quantitative statement on the agreement of the considered FI as computed  
29 from radiosonde and MWRP retrieved profiles, we process the data in order to match the  
30 independent datasets and compute statistical scores, such as the average (AVG), standard  
31 deviation (STD), and root-mean-square (RMS) differences, the correlation coefficient (COR),  
32 and finally the slope (SLP) and intercept (INT) of a least-square linear fit. The statistical

1 scores for K-index in Whistler are summarized in Figure 6. For higher values (K-index > 15),  
2 it is evident that both NNz and 1-DVAR agree fairly well with the values computed from  
3 radiosondes. For lower values the 1-DVAR gives much better agreement than NNz, as  
4 anticipated above. Overall, the comparison in Whistler of K-index computed from 1-DVAR  
5 temperature and humidity retrievals with K-index computed from radiosonde profiles shows  
6 RMS error within 6.1 K (less than 10% of the total range) with a correlation coefficient better  
7 than 0.9. With respect to NNz retrievals, 1-DVAR reduces significantly both the systematic  
8 (AVG roughly from 10 to 1 K) and the random (STD by a factor of 1.5, RMS by a factor of 2)  
9 error components. Note that the results for NNz are still fairly good (0.88 correlation), and  
10 tend to agree with 1-DVAR for higher values, where the K-index is more interesting for  
11 forecasting purposes.

12 Similarly, Figures 7 and 8 show the scatter plots and statistical scores for the other forecast  
13 indices. For Jefferson Index, Total Totals, KO, Showalter Index, Lifted Index, and STT  
14 similar considerations as for K-index apply, i.e. the comparison between FI from radiosonde  
15 and MWRP retrievals results in (a) a significant improvement of the statistical scores for 1-  
16 DVAR with respect to NNz, and (b) correlation coefficients better than 0.9 and RMS within  
17 10% of the range (considering 1-DVAR). As for the K-index, results for NNz are still fairly  
18 good (correlation between 0.8-0.9 depending on FI), and tend to agree with 1-DVAR in the  
19 most significant range. For the Fog Threat and T1 Gust, the correlation coefficients are much  
20 lower (respectively 0.8 and 0.7, considering 1-DVAR) and the RMS exceeds 10% of the  
21 range (respectively 12% and 19%, considering 1-DVAR). The improvement brought by 1-  
22 DVAR with respect to NNz is significant for T1 Gust (a factor of 1.5 for STD and RMS, a  
23 factor ~3 for correlation), while it becomes negligible for the Fog Threat. The latter result can  
24 be explained by looking at the similar results for NNz and 1-DVAR in Fig.1 for the lower  
25 levels, which mainly determine the value of the Fog threat index.

26 The statistics of the difference between FI computed from radiosonde and MWRP retrievals  
27 in Whistler are summarized in Table 2. In addition to the FI discussed above, Table 2 shows  
28 the results for four more FI, namely the Convective Available Potential Energy (CAPE), the  
29 Microburst Day Potential Index (MDPI), the Thompson Index, and finally the TQ Index. For  
30 CAPE, the 1-DVAR retrievals show 0.94 correlation coefficient and 102.5 J/kg RMS (less  
31 than 10% of the range), with an improvement factor of 1.7 and 3.7, respectively, with respect  
32 to NNz. For MDPI, results are similar for NNz and 1-DVAR retrievals, showing 0.80-0.83

1 correlation coefficient, respectively. For Thompson Index and TQ Index, 1-DVAR retrievals  
2 show correlation coefficient exceeding 0.9 and RMS within 10% of the total range, somewhat  
3 better than the NNz retrievals. Thus, similarly to other FI, CAPE, MDPI, Thompson Index,  
4 and TQ Index show good correlation between radiosondes and MWRP estimates (either NNz  
5 or 1-DVAR), with a tangible improvement for 1-DVAR with respect to NNz.

6 Similarly, Figures 9-11 and Table 3 show the results for the analysis at the other site, MOL-  
7 RAO in Lindenberg. At MOL-RAO, four types of MWRP retrievals are available, as already  
8 seen in Figure 1. FI are computed from three of those MWRP retrievals (NNz, 1-DVAR, and  
9 ObsREG), and then compared to the FI computed from radiosondes. Figure 9 shows the  
10 results for KI, for which the three MWRP retrievals agree fairly well, with 0.81-0.88  
11 (ObsREG and NNz/1-DVAR, respectively) correlation coefficient with respect to radiosonde  
12 values. Figures 10 and 11 show the results for Total Totals, STT, KO, Lifted Index, Showalter  
13 Index, Fog Threat, T1 Gust, and Jefferson Index. These results are consistent with the ones in  
14 Whistler for the most. In terms of correlation coefficient, 1-DVAR retrievals usually  
15 outperforms the other two, though the differences are less significant than in Whistler.  
16 However, 1-DVAR shows the lowest correlation of the three retrievals for two FI (CAPE and  
17 Fog Threat), while it shows lower correlation than NNz for a TQ Index.

18

## 19 **5 Summary and conclusions**

20 Forecast indices based on radiosonde soundings have been developed over many decades as  
21 local weather prediction tools. However, FI typically lose their value during six hour and  
22 longer intervals between traditional radiosonde soundings. Continuous tropospheric  
23 thermodynamic profiles can be retrieved on a minute time scale from a ground-based  
24 microwave radiometer profiler (MWRP) working in the 20–60 GHz range. Forecast indices  
25 (FI) developed for radiosonde TPU profiles can be derived from the MWRP thermodynamic  
26 profiles. The present analysis demonstrates good agreement between FI derived from MWRP  
27 and radiosonde soundings. The analysis is performed for two midlatitude sites: one residing in  
28 a low-elevation flat rural area in Central Europe (Lindenberg, Germany) and the other in a  
29 mountainous environment along the Pacific Ranges of the Coast Mountains in western North  
30 America (Whistler, Canada). The analysis revealed:

- 31 • There is good agreement between MWRP and radiosonde-derived FI at both sites,  
32 with correlation coefficients usually exceeding 0.8.

1 • FI derived from 1-DVAR retrievals usually outperform neural network and  
2 observation-based regression retrievals in terms of correlation, mean, and random difference  
3 with respect to FI values derived from radiosondes.

4 • FI time series derived from MWRP retrievals provide promising new tools for local  
5 high impact weather prediction (Madhulatha et al, 2013) based on uninterrupted surveillance  
6 of local tropospheric thermodynamics in all weather conditions (Cimini et al, 2011; Ware et  
7 al, 2013; Xu et al, 2014), capturing the entire diurnal cycle and providing fresh and timely  
8 data to forecasters.

9 Therefore, we conclude that MWRP retrievals are able to deliver valuable FI, with the certain  
10 advantage (with respect to radiosondes) of nearly continuous update. FI time series are  
11 promising new tools for high impact local weather forecasting, complementing and  
12 augmenting 6/12-hr indices derived from radiosonde soundings.

13

#### 14 **Acknowledgements**

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17 Wetterdienst) conducted microwave profiler and radiosonde data collection in Whistler and  
18 Lindenberg, respectively, and provided grant support for data analysis.

19

#### 20 **Appendix A: Definitions of Forecast Indices**

21 In this Appendix we summarise the definitions of the forecast indices considered in our  
22 analysis. In the following definitions,  $T_{xxx}$  is the temperature at the pressure level xxx (in mb),  
23  $Td_{xxx}$  is dew point temperature,  $\theta_{e_{xxx}}$  is the equivalent potential temperature,  $\theta_{WB_{xxx}}$  is the wet  
24 bulb potential temperature at the same pressure level. The Forecast Index definition below  
25 were extracted from review papers (Peppler, 1998; Haklander and Van Delden, 2003; de  
26 Coning et al., 2010) as well as from American Meteorological Society glossary (AMS, 2013)  
27 and RAOB software manual. According to Haklander and Van Delden (2003), the various  
28 forecast indices are a combination of three types, the first accounting for pure conditional  
29 instability, the second accounting for pure latent instability, and the third accounting for pure  
30 potential instability of certain atmospheric layers. In our analysis, we have considered at least  
31 one for each type.

1

## 2 **CAPE**

3 The Convective Available Potential Energy (CAPE) defines the maximum energy available to  
4 an ascending air parcel, and it is often used to indicate instability and the possibility of  
5 thunderstorms. There exists many different definitions of CAPE in literature (Haklander and  
6 Van Delden, 2003). Here, CAPE is calculated by integrating vertically the local buoyancy of  
7 a parcel (expressed introducing the virtual temperature of the parcel  $T_{v_p}$  and that of the  
8 environment  $T_{v_e}$ ) from the level of free convection (LFC) to the equilibrium level (EL):

$$9 \quad CAPE = -R_d \int_{LFC}^{EL} (T_{v_p} - T_{v_e}) d(\ln p)$$

10 where  $R_d = 287,05 \text{ J/kg}\cdot\text{K}^{-1}$  is the gas constant for dry air and CAPE is measured in joules per  
11 kilogram of air (J/kg). Any value greater than 0 J/kg indicates instability and the possibility of  
12 thunderstorms.

13

## 14 **Fog Threat**

15 The Fog Threat (FT) index indicates the potential for radiation fog and it is based on the  
16 definition of Fog Point (FP), which is the temperature at which radiation fog will form. The  
17 fog point is determined by following the saturation mixing ratio line from the dew point curve  
18 at the lifting condensation level (LCL) to the surface temperature. Then, the Fog Threat is  
19 given by the difference of the wet bulb potential temperature at 850 mb  $\theta_{WB850}$  and the Fog  
20 Point computed as above:

$$21 \quad FT = \theta_{WB850} - FP$$

22 The potential for radiation fog is low for  $FT > 3$ , while it becomes high for  $FT < 0$ .

23

## 24 **Jefferson index**

25 The Jefferson index (JI) was designed originally for maritime and arid areas (Haklander and  
26 Van Delden 2003, and references therein). JI is defined as:

$$27 \quad JI = 1.6 * \theta_{WB850} - T_{500} - 0.5 * (T_{700} - Td_{700}) - 8$$

1 Non-frontal thunderstorms can be expected for values above 28. Significant showers with  
2 thunderstorm are expected for values above 30.

3

#### 4 **K-index**

5 The K-index is due to George (1960) and it is defined by:

$$6 \text{ KI} = (T_{850} - T_{500}) + Td_{850} - (T_{700} - Td_{700})$$

7 The first term is the lapse rate, while the second and third are related to the moisture between  
8 850 and 700 mb, and are strongly influenced by the temperature–dewpoint spread at the 700  
9 mb level. The K-index increases with decreasing static stability between 850 and 500 hPa,  
10 increasing moisture at 850 hPa, and increasing relative humidity at 700 hPa. The higher the K  
11 index, the higher the probability of thunderstorms. As K-index increases from a value of 20 or  
12 so, the likelihood of showers and thunderstorms is expected to increase. The K-index was  
13 developed for forecasting air mass thunderstorms, particularly useful in predicting non-frontal  
14 thunderstorm situations.

15

#### 16 **KO index**

17 KO index was developed for estimating thunderstorm potential in Europe (Andersson et al.,  
18 1989). The KO index describes the potential instability between lower and higher levels of the  
19 atmosphere and it is thus based on the equivalent potential temperature  $\theta_e$  as:

$$20 \text{ KO} = ( (\theta_{e_{500}} + \theta_{e_{700}}) - (\theta_{e_{850}} + \theta_{e_{1000}}) ) / 2$$

21 If the surface level is above 1000 mb, then  $\theta_{e_{\text{srf}}}$  is used instead of  $\theta_{e_{1000}}$ . The KO is more  
22 sensitive to moisture than other stability indices and it is best used in cooler, moist climates.  
23 The thunderstorm potential increases as the KO index decreases. Values smaller than 2  
24 generally indicate strong thunderstorm potential.

25

#### 26 **Lifted Index**

27 The Lifted index (LI), developed by Galway (1956), is nominally identical to the Showalter  
28 index, except for the determination of the level from which the parcel is lifted.

$$29 \text{ LI} = T_{500} - T_L$$

1 The LI was defined by lifting the parcel adiabatically from the midpoint of the surface layer to  
2 500 mb, where its temperature, considered the updraft temperature within a developing cloud,  
3 was compared to that of the environment. The parcel being lifted is defined by the dry adiabat  
4 running through the predicted surface afternoon temperature maximum and the mean mixing  
5 ratio in the lowest 900 m. The values of this index tend to be somewhat lower than those of  
6 Showalter.

7

### 8 **Microburst day potential index (MDPI)**

9 The microburst day potential index (MDPI) was developed in part on the results from the  
10 Microburst and Severe Thunderstorm (MIST) project (Atkins and Wakimoto, 1991). MDPI is  
11 based on the vertical profiles of equivalent potential temperature and it is defined follows:

$$12 \text{ MDPI} = (\text{Max } \theta_e(\text{Sfc}-850\text{mb}) - \text{Min } \theta_e(660-500\text{mb})) / 30$$

13 MDPI was designed to determine likely and unlikely environments for downbursts. For MDPI  
14 values greater than or equal to one, microbursts are likely.

15

### 16 **Showalter index**

17 The Showalter index (SI) was designed originally for thunderstorm forecasting in the  
18 southwester US (Showalter 1947). It estimates the potential instability of the 850 to 500 mb  
19 layer by measuring the buoyancy at 500 mb of an air parcel lifted to that level. Thus, it is  
20 defined as:

$$21 \text{ SI} = T_{500} - T_L$$

22 where  $T_L$  is the temperature ( $^{\circ}\text{C}$ ) of a parcel lifted from 850 to 500 mb, dry-adiabatically to  
23 saturation and moist-adiabatically above that. As the index decreases to zero and below, the  
24 likelihood of showers and thunderstorms is considered to increase. SI values  $\leq +3$  are  
25 indicative of possible thunderstorm activity, while values  $\leq -3$  are associated with severe  
26 convective activity. The SI has been one of the most frequently applied stability indices.

27

### 28 **S index (STT)**

1 The S index (STT) was introduced by the German Military Geophysical Office as an  
2 improvement on the Total Totals index (Haklander and Van Delden, 2003 and references  
3 therein) including a variable parameter A based on Vertical Totals (VT). The S index is  
4 defined as:

$$5 \quad STT = TT - (T_{700} + Td_{700}) - A = T_{850} + Td_{850} - 2 \cdot T_{500} - (T_{700} - Td_{700}) - A$$

6 where TT indicates Total Totals index (see below) and A depends on VT such that it  
7 penalizes cases with low values of VT (i.e. low vertical temperature gradients):

$$8 \quad A = 0 \text{ (if } VT > 25\text{); } 2 \text{ (if } 22 \leq VT \leq 25\text{); } 6 \text{ (if } VT < 22\text{)}$$

9 Note that the S index takes the same variables into account as the K Index, but in other  
10 proportions, and thus it can also be written as:

$$11 \quad STT = KI - T_{500} - A$$

12

### 13 **T1 Gust**

14 The T1 Gust (also called Dry Stability Index) method was developed with the intent of giving  
15 forecasters a way to estimate maximum thunderstorm wind gusts (Fawbush and Miller, 1954).

16 The T1 method is still used to predict the maximum wind gust in air mass thunderstorms,  
17 relying on evidence that most convective wind gusts at the surface appear to result from  
18 downdraft air originating in the lower portion of a thunderstorm. Thus, the T1 method is  
19 computed as the difference between the temperature of a parcel of moist surface air raised  
20 moist adiabatically to 600 mb ( $T_{MA600}$ ) and the observed dry bulb temperature at the 600 mb  
21 level.

$$22 \quad T1 = T_{MA600} - T_{600}$$

23 In case of a temperature inversion within 150-200 hPa above the surface, the moist adiabat is  
24 followed from the warmest point in the inversion to 600 mb (Miller, 1972). Finally, the speed  
25 of maximum wind gust (in knots) is given by the empirical formula  $V \approx 13 \cdot \sqrt{T1}$ .

26

### 27 **Thompson Index**

28 The Thompson Index (TI) is primarily used to determine thunderstorm potential in the Rocky  
29 Mountains. It is defined as:

1  $TI = KI - LI$

2 The Thompson Index should be an improvement of KI, since KI neglects latent instability  
3 below 850 hPa. Thunderstorm potential is considered weak for values below 30, while it  
4 becomes strong for values greater than 35.

5

## 6 **Total Totals**

7 Total Totals (TT) index is attributable to Miller (1972) and it is defined by the combination of  
8 the vertical totals ( $VT = T_{850} - T_{500}$ ) and the cross totals ( $CT = Td_{850} - T_{500}$ ), resulting in:

9  $TT = T_{850} + Td_{850} - 2 \cdot T_{500}$

10 The TT index is commonly used as a severe weather indicator. The higher the number, the  
11 more unstable the atmosphere. Values lower than 45°C generally indicate weak thunderstorm  
12 potential, while values larger than 55°C indicate high possibility of severe thunderstorms,  
13 though value interpretation varies with season and location.

14

## 15 **TQ Index**

16 The TQ index (TQ) is used to assess the potential for low-topped convection. It is defined as:

17  $TQ = (T_{850} + Td_{850}) - 1.7 \cdot (T_{700})$ .

18 Values larger than 12 indicate unstable lower troposphere where thunderstorm and rainfall are  
19 possible outside of stratiform clouds, while for values larger than 17 thunderstorm and rainfall  
20 are possible in presence of stratiform clouds.

21

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- 22

1 Table 1: Summary of MWRP characteristics.

Channels	22
Frequencies (GHz)	22.234, 22.5, 23.034, 23.834, 25.0, 26.234, 28.0, 30.0, 51.248, 51.76, 52.28, 52.804, 53.336, 53.848, 54.4, 54.94, 55.5, 56.02, 56.66, 57.288, 57.964, 58.8
Bandwidth (MHz)	300
Elevation	15-90°
Azimuth	Fixed

2

3 Table 2: Statistics of the difference between FI computed from radiosonde and MWRP  
 4 retrievals (NNz and 1-DVAR) in Whistler (64 radiosondes). Here are shown average (AVG)  
 5 FI difference (radiosonde-MWRP), standard deviation (STD), root-mean-square (RMS), and  
 6 correlation coefficient (COR).

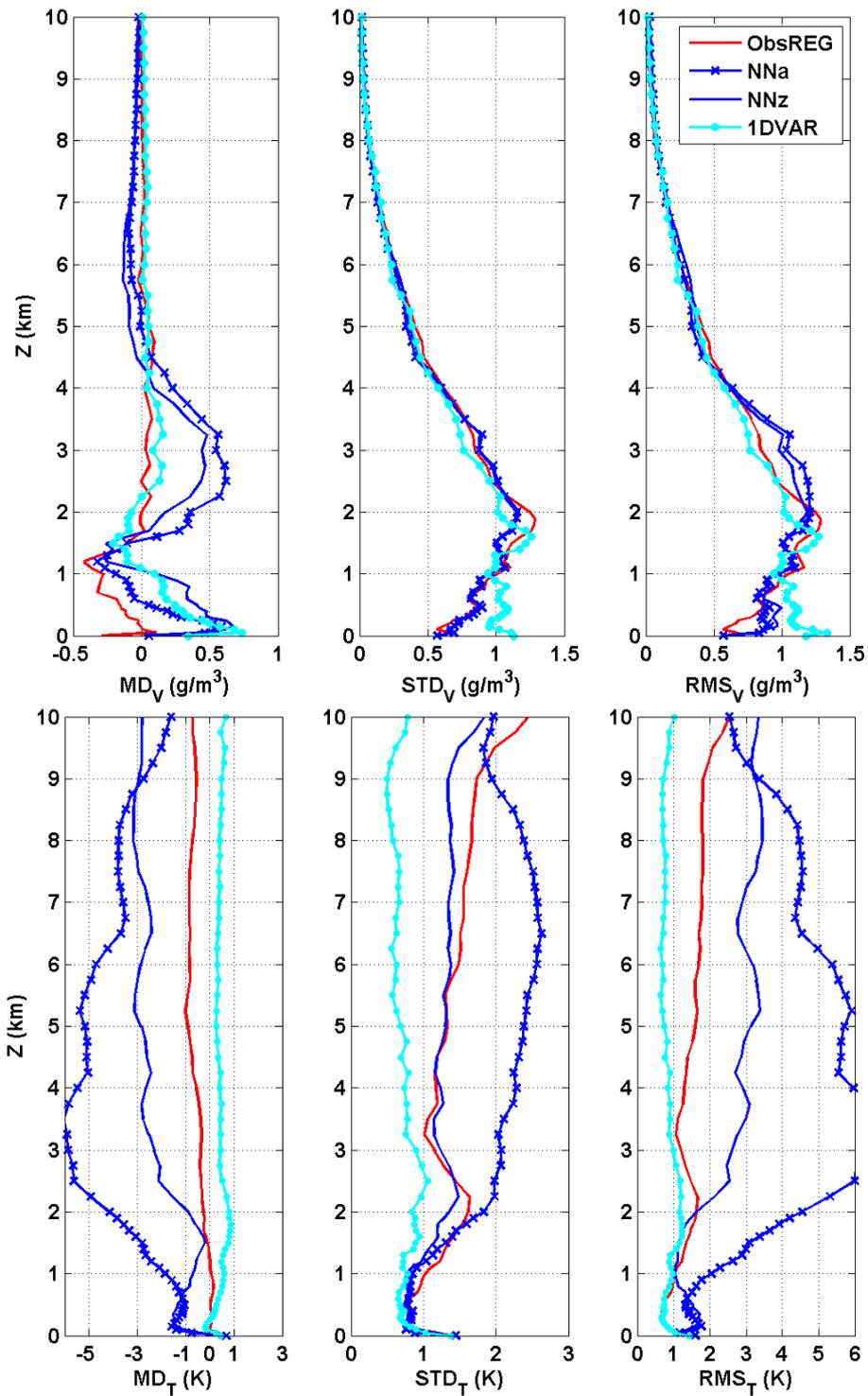
	NNz				1-DVAR			
	AVG	STD	RMS	COR	AVG	STD	RMS	COR
<b>CAPE</b>	-283.72	216.97	379.04	0.53	-49.03	87.34	102.53	0.94
<b>Fog Threat</b>	0.45	2.37	2.41	0.80	0.45	2.37	2.41	0.80
<b>Jefferson Index</b>	-6.75	5.16	8.54	0.83	1.08	3.33	3.50	0.92
<b>K-index</b>	-10.25	9.23	13.85	0.88	1.05	6.15	6.24	0.91
<b>KO</b>	5.41	2.28	5.91	0.91	0.60	1.79	1.89	0.94
<b>Lifted Index</b>	5.91	2.36	6.41	0.91	1.76	1.64	2.41	0.96
<b>MDPI</b>	-0.11	0.11	0.16	0.80	0.00	0.11	0.11	0.83
<b>Showalter Index</b>	3.40	1.96	3.95	0.84	-1.10	1.75	2.07	0.92
<b>STT</b>	-16.13	11.35	19.82	0.81	2.36	7.54	7.91	0.91
<b>T1Gust</b>	7.71	10.82	13.32	0.24	0.15	7.79	7.79	0.70
<b>Thompson Index</b>	-16.17	10.85	19.58	0.87	-0.73	6.19	6.23	0.94
<b>Total Totals</b>	-7.30	3.94	8.34	0.85	1.16	3.48	3.67	0.91
<b>TQ Index</b>	-5.61	4.41	7.17	0.81	1.07	3.26	3.44	0.90

7

1 Table 3: As in Table 2 but for Lindenberg (233 radiosondes). Average (AVG) FI difference  
 2 (radiosonde-MWRP), standard deviation (STD), root-mean-square (RMS), and correlation  
 3 coefficient (COR) are shown.

	NNz			1-DVAR			ObsREG		
	AVG	STD	COR	AVG	STD	COR	AVG	STD	COR
CAPE	-323.26	354.99	0.69	-9.90	259.64	0.61	14.07	217.74	0.70
Fog Threat	0.82	3.08	0.79	-0.42	3.27	0.76	-0.55	3.24	0.77
Jefferson Index	-5.40	4.53	0.89	0.14	4.09	0.90	-1.32	5.96	0.81
K-index	-8.67	8.80	0.88	0.00	8.26	0.88	-1.81	10.92	0.82
KO	2.99	2.58	0.90	-0.09	2.38	0.92	0.95	3.15	0.85
Lifted Index	3.39	1.76	0.93	0.22	1.70	0.94	1.09	1.85	0.92
MDPI	-0.04	0.14	0.83	0.03	0.11	0.90	0.04	0.19	0.68
Showalter Index	2.31	2.14	0.89	-0.21	1.73	0.92	1.19	3.08	0.74
STT	-13.09	10.05	0.89	0.25	8.49	0.90	-3.86	12.26	0.82
T1Gust	-1.72	9.71	0.60	0.06	7.53	0.72	-0.80	9.17	0.60
Thompson Index	-12.04	9.35	0.91	-0.20	8.60	0.90	-2.87	11.27	0.85
Total Totals	-5.13	4.40	0.87	0.32	3.50	0.90	-2.31	5.39	0.74
TQ Index	-4.07	3.96	0.87	0.42	3.83	0.85	-0.93	4.35	0.80

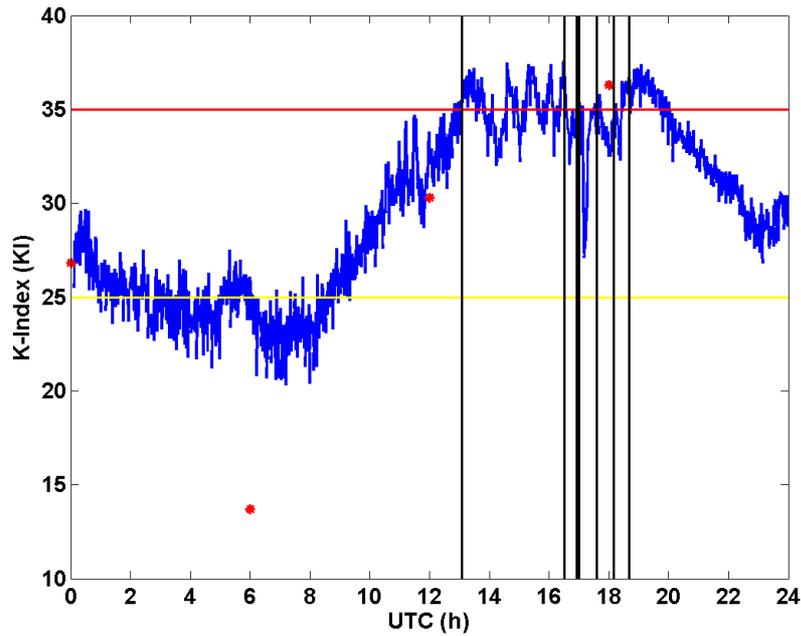
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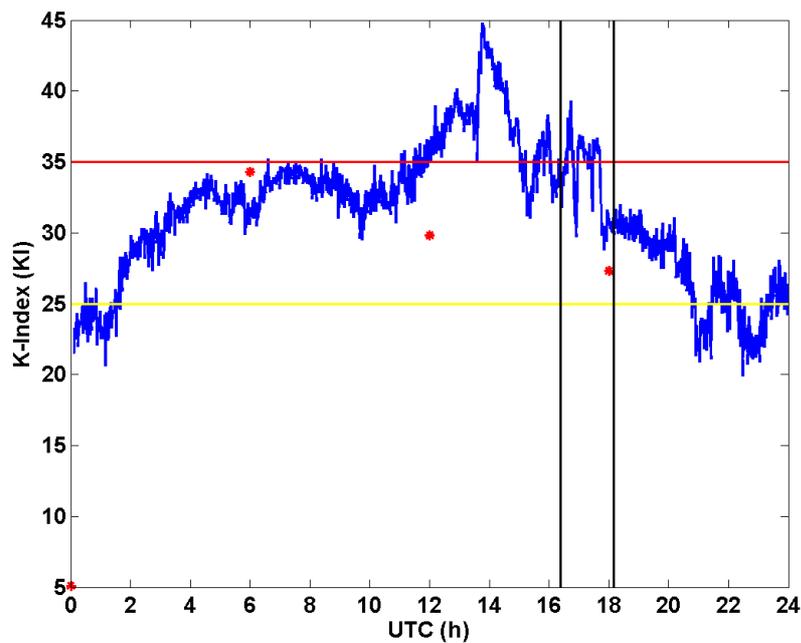
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3 Figure 1: Statistics of water vapour density (top) and temperature (bottom) profiles retrieved  
 4 with NN, ObsREG, and 1-DVAR, as compared to radiosondes (233 cases). (Left) Mean  
 5 difference (radiosonde minus retrievals). (Center) STD difference. (Right) RMS difference.  
 6 The legend in the top-right corner indicates the line color/style coding.

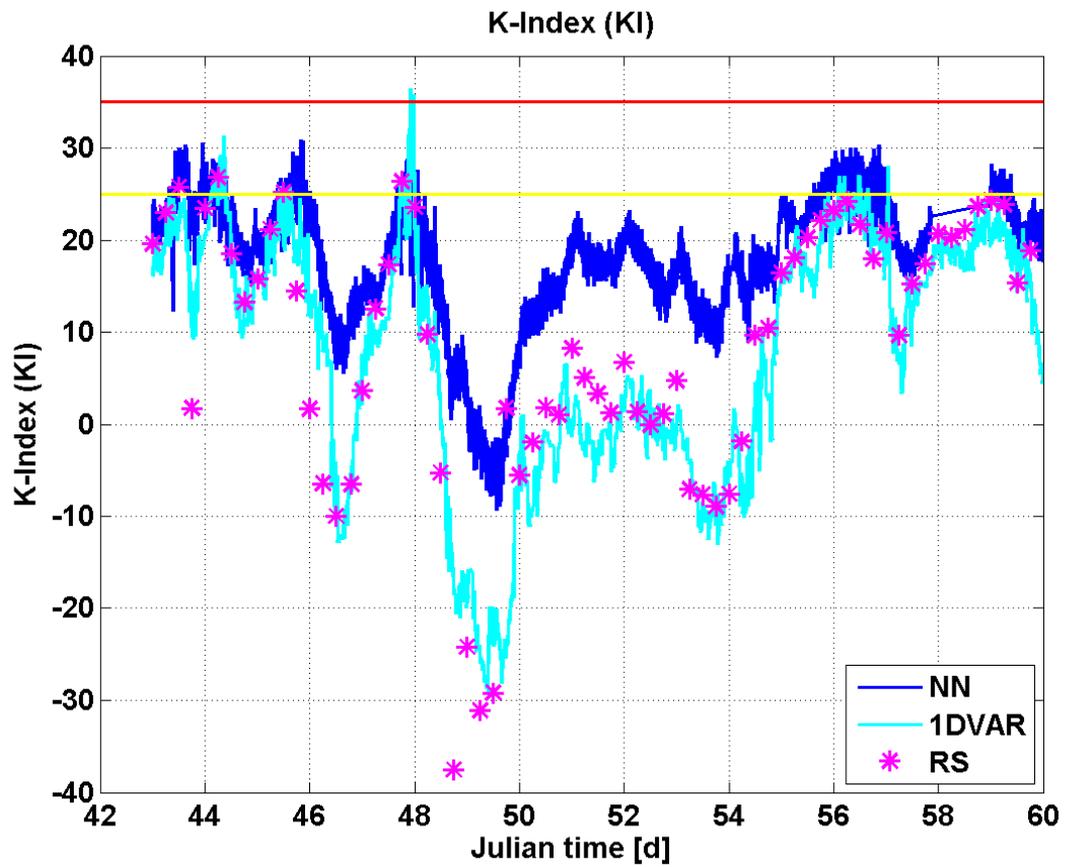


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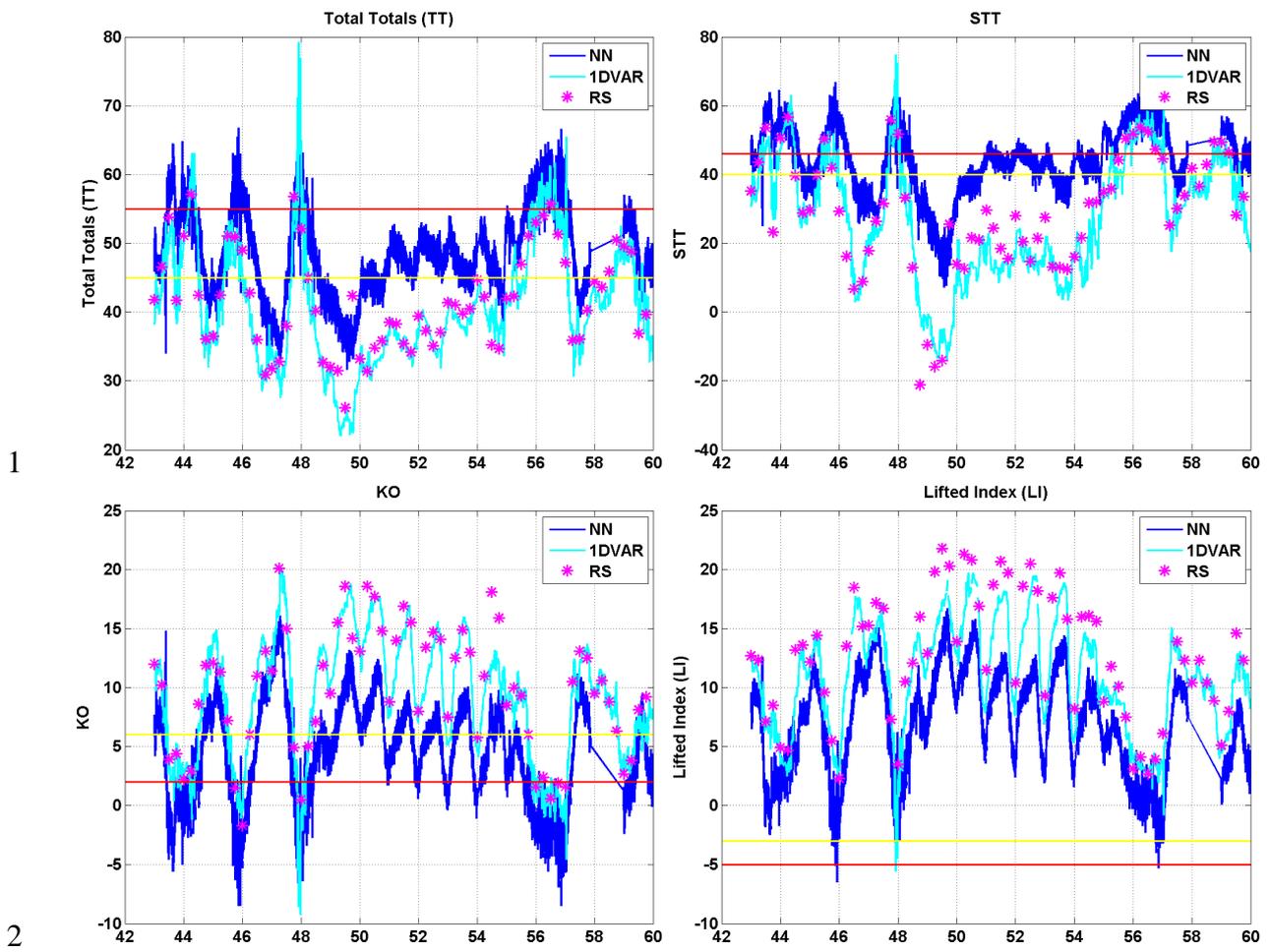
3 Figure 2: Top: 24-hour time series of K-index computed from MWRP NNz retrievals (blue  
 4 line), and radiosonde profiles (red dots) for August 12, 2010. Thunder near Lindenberg started  
 5 at 13:05 and lasted until 18:40 UTC; vertical black lines indicate the time of thunder  
 6 detection. Yellow and red lines show the boundaries for weak-to-moderate and moderate-to-  
 7 strong thunderstorm potential thresholds, respectively. Bottom: case of August 15, 2010.  
 8 Thunder near Lindenberg was reported between 16:10 and 18:05 UTC.



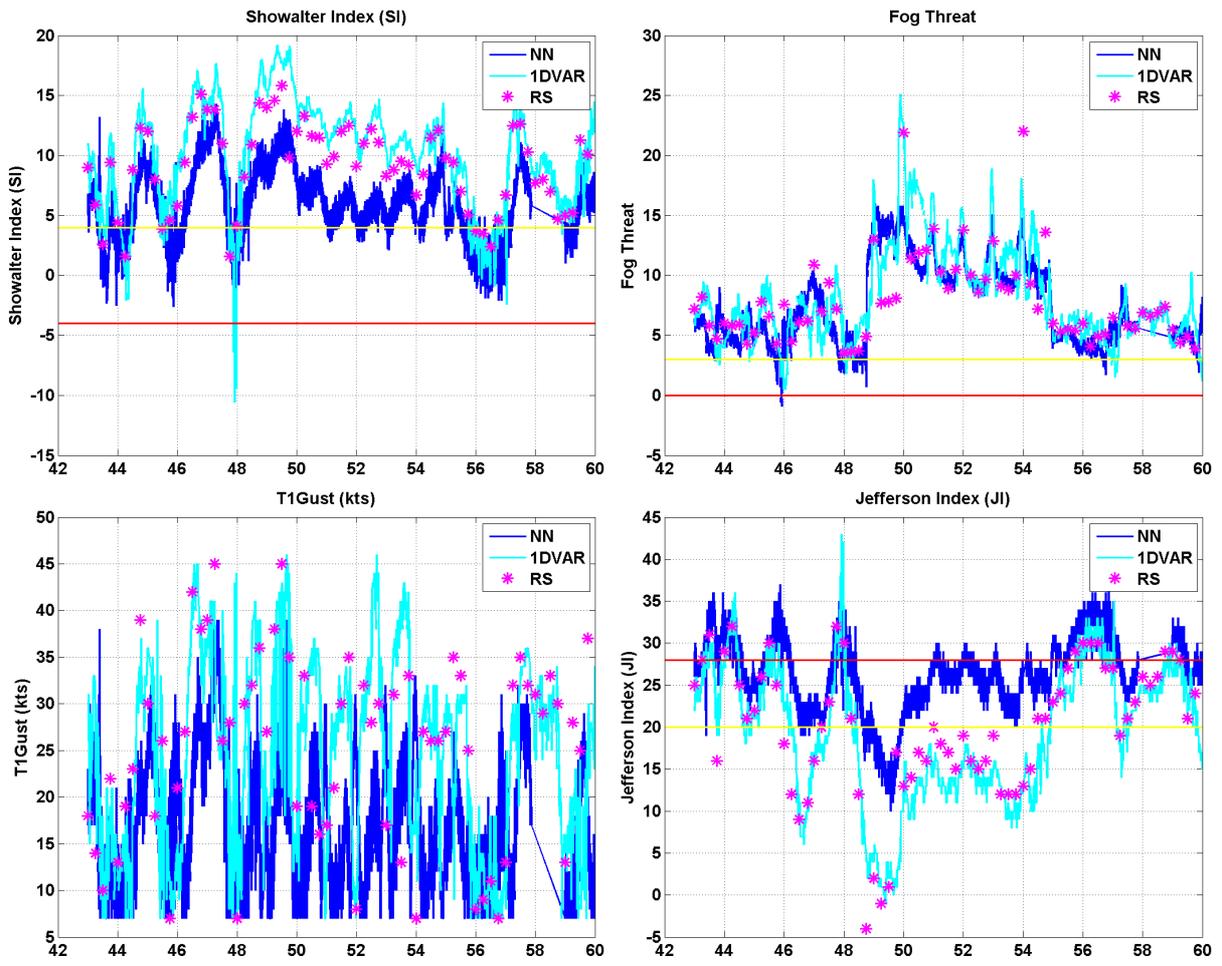
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2 Figure 3: 17-day long time series of K-index in Whistler. K-index from radiosondes (RS) and  
 3 from MWRP NNz and 1-DVAR retrievals are indicated with magenta stars, blue and cyan  
 4 line, respectively. The horizontal yellow and red lines indicate moderate and high  
 5 thunderstorm potential, respectively.

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3 Figure 4: As in Figure 3, but for (clockwise from top-left panel) Total Totals, STT, LI, and  
4 KO. The horizontal yellow and red lines indicate thresholds for moderate and high potential,  
5 respectively.



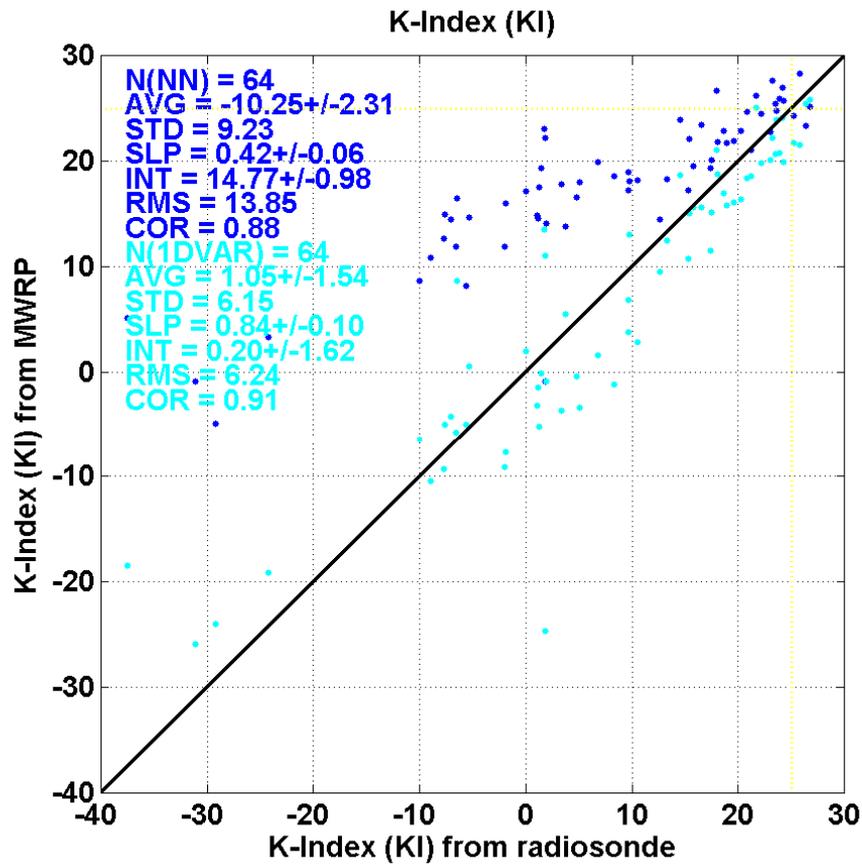
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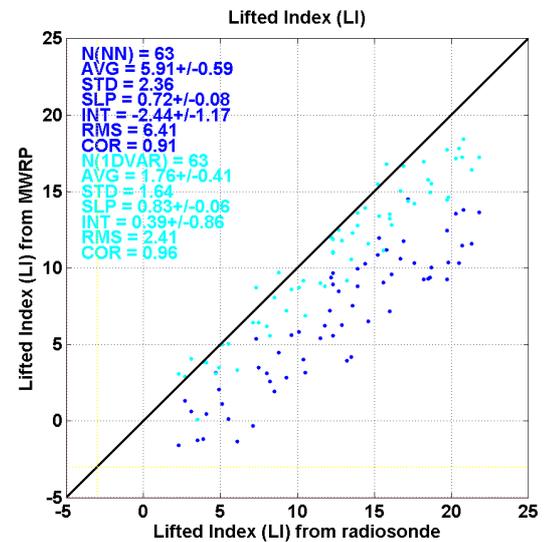
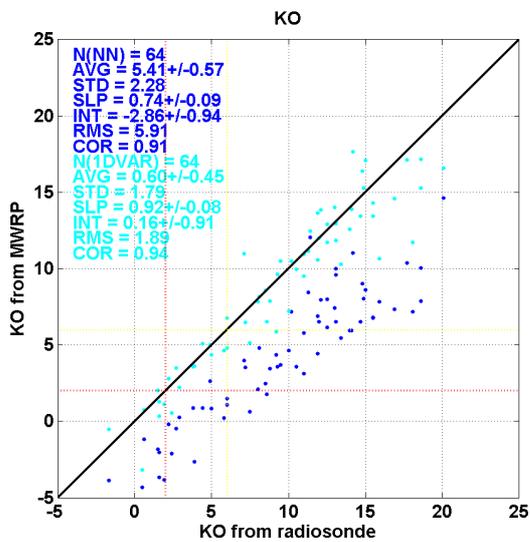
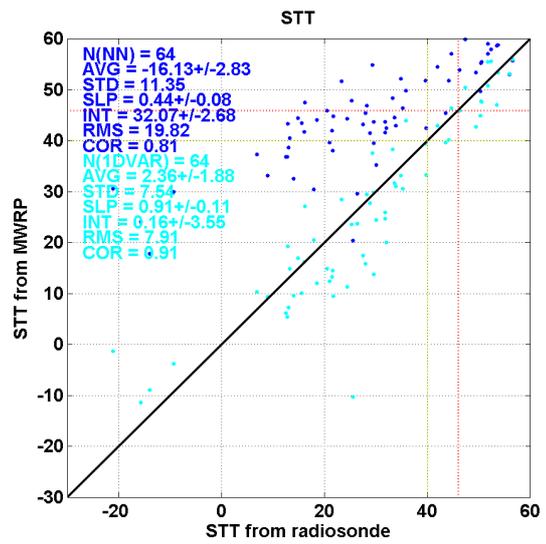
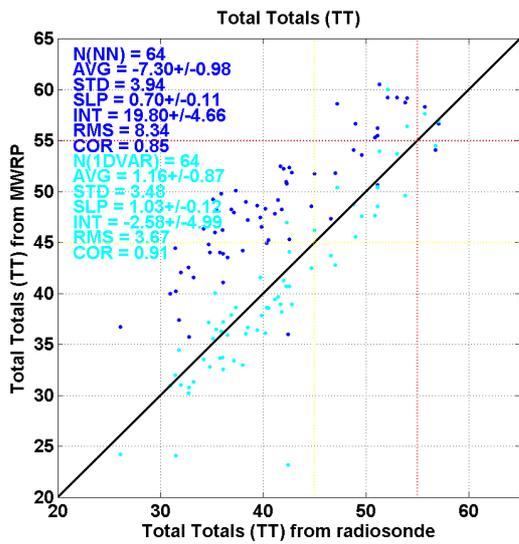
3 Figure 5: As in Figure 3, but for (clockwise from top-left panel) Showalter Index, Fog Threat,  
 4 T1 Gust, and Jefferson index. The horizontal yellow and red lines indicate thresholds for  
 5 moderate and high potential, respectively (where applicable).

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 2 Figure 6: Scatter plot of K-index values computed from radiosonde and MWRP retrieved  
 3 profiles (NNz in blue, 1-DVAR in cyan) and respective statistics: average (AVG), standard  
 4 deviation (STD), and root-mean-square (RMS) differences, correlation coefficient (COR),  
 5 slope (SLP) and intercept (INT) of a least-square linear fit. AVG, STD, INT, RMS are in  
 6 Kelvin. SLP and COR are unitless. Numbers after the  $\pm$  sign indicate the 95% confidence  
 7 interval.

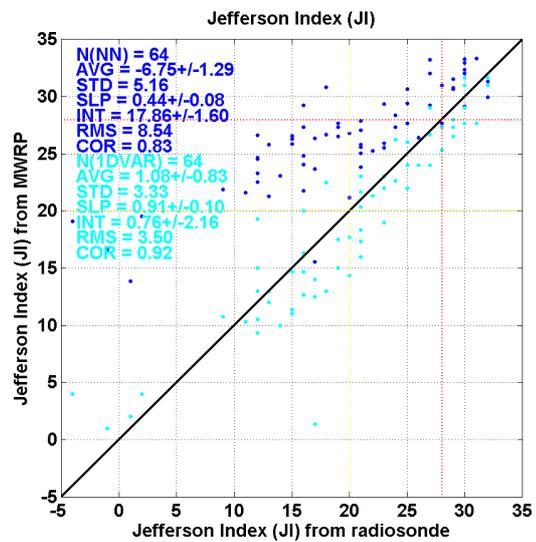
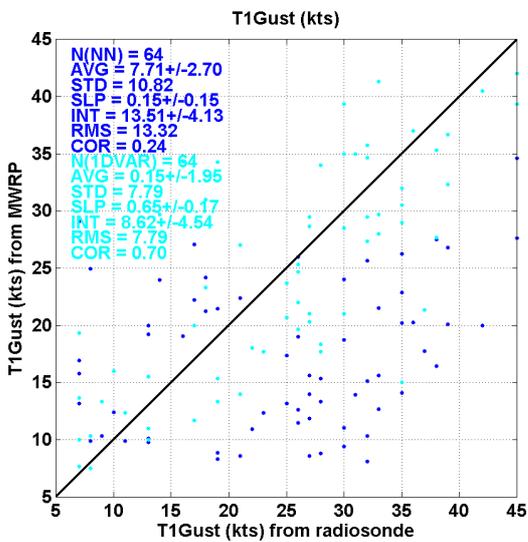
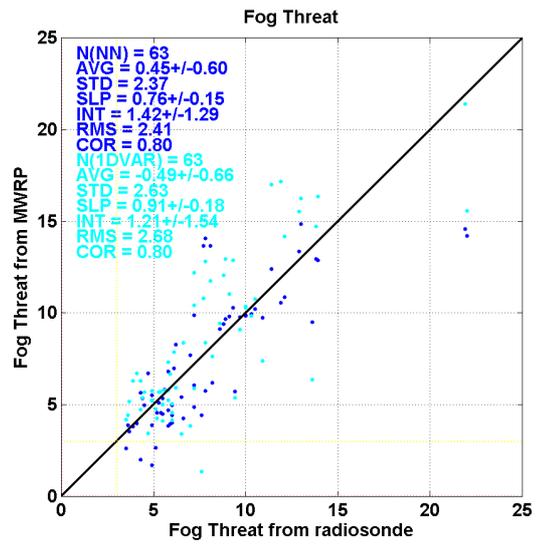
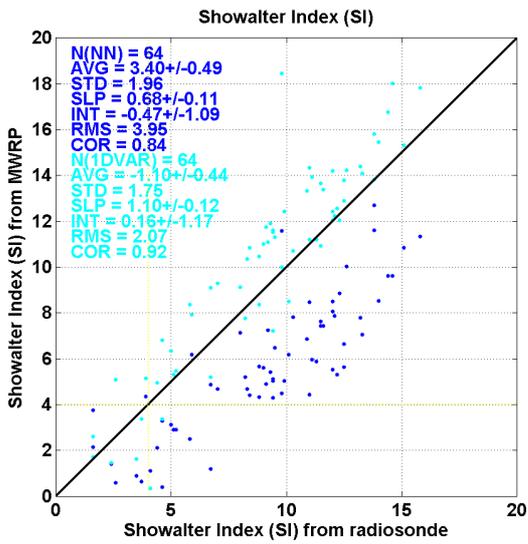


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3 Figure 7: As in Figure 6, but for (clockwise from top-left panel) Total Totals, STT, KO,  
 4 Lifted Index. Dotted yellow and red lines indicate thresholds for moderate and high potential,  
 5 respectively (where applicable).

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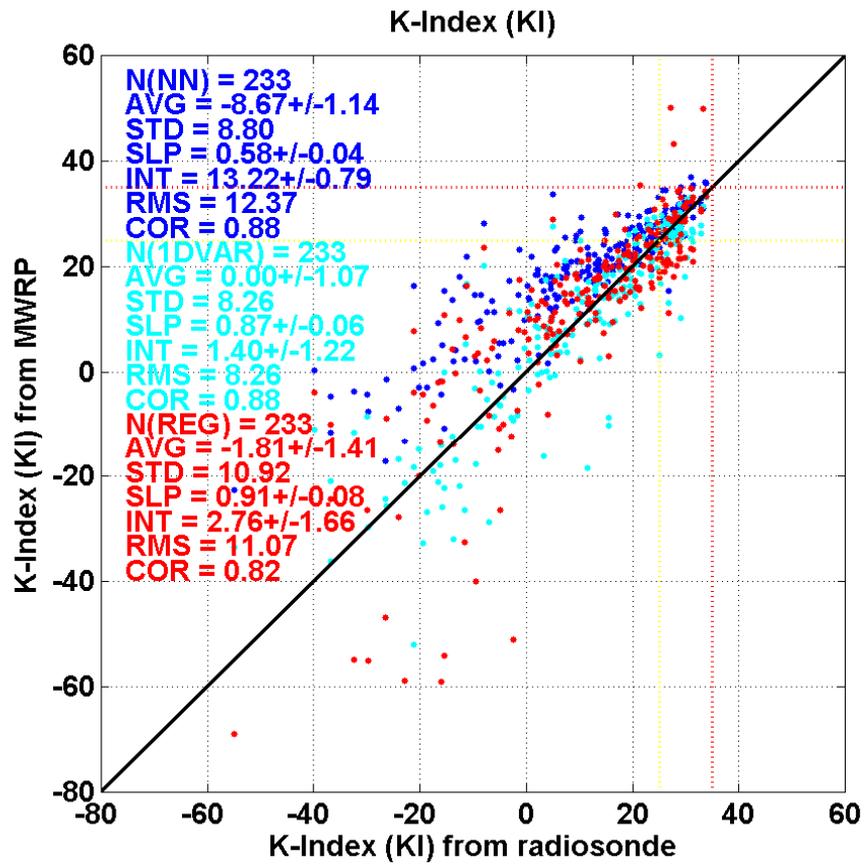


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3 Figure 8: As in Figure 6, but for (clockwise from top-left panel) Showalter Index, Fog Threat,  
 4 T1 Gust, and Jefferson Index. Dotted yellow and red lines indicate thresholds for moderate  
 5 and high potential, respectively (where applicable).

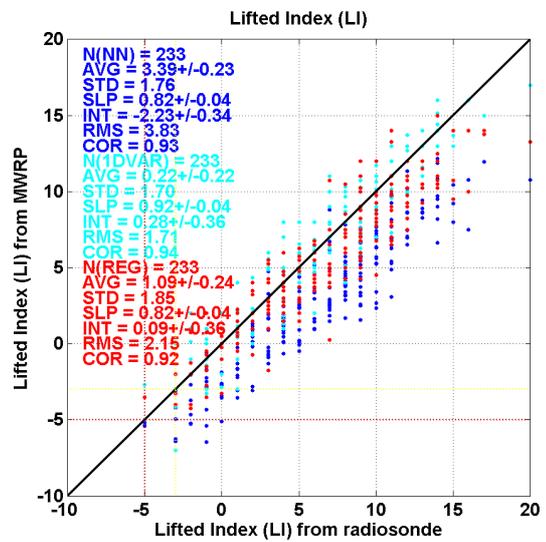
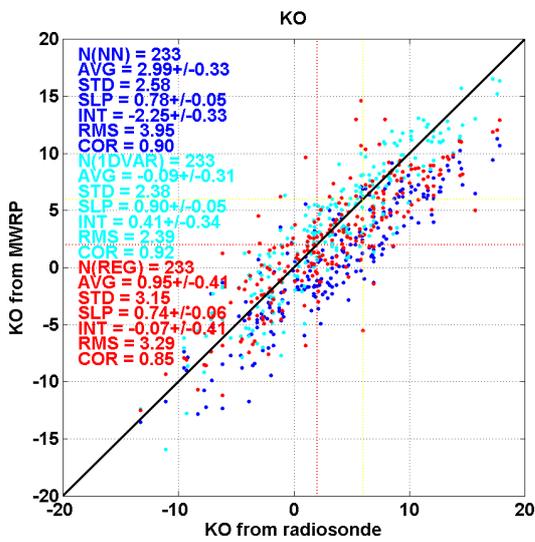
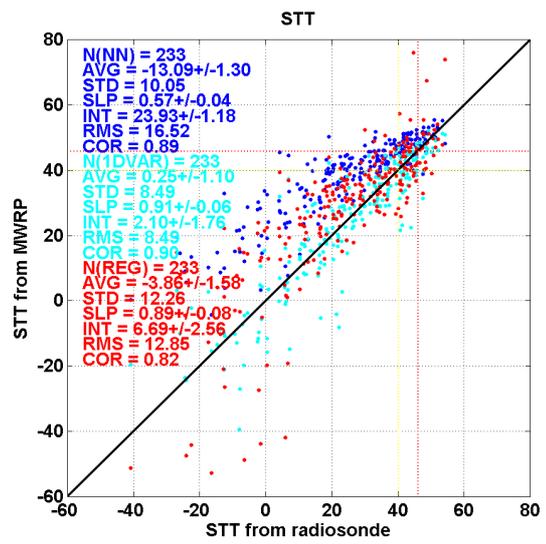
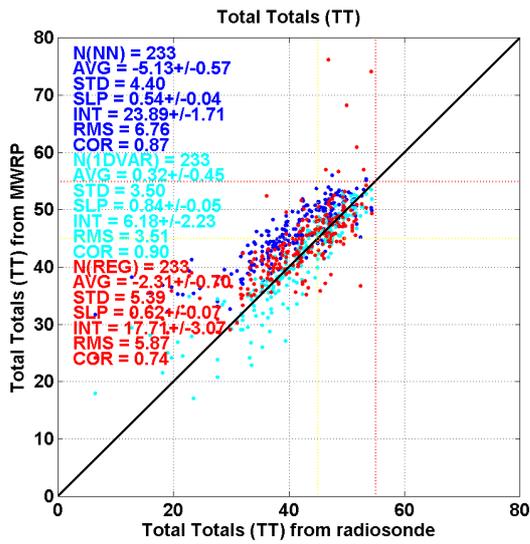
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2 Figure 9: Scatter plot of K-index values computed from radiosonde and MWRP retrieved  
 3 profiles (NNz in blue, 1-DVAR in cyan, REG in red) and respective statistics: average  
 4 (AVG), standard deviation (STD), and root-mean-square (RMS) differences, correlation  
 5 coefficient (COR), slope (SLP) and intercept (INT) of a least-square linear fit. AVG, STD,  
 6 INT, RMS are in Kelvin. SLP and COR are unitless. Numbers after the  $\pm$  sign indicate the  
 7 95% confidence interval.

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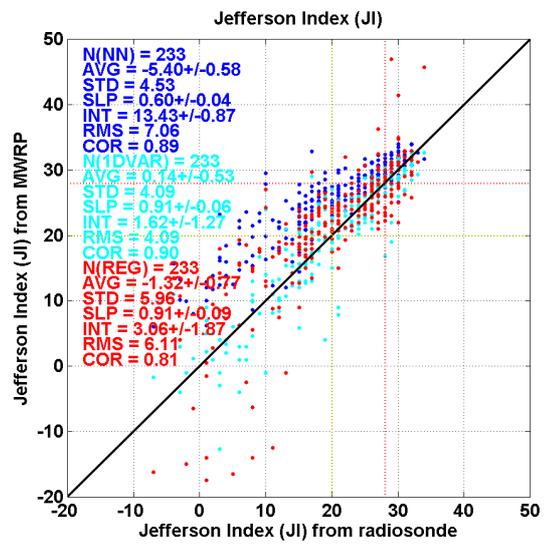
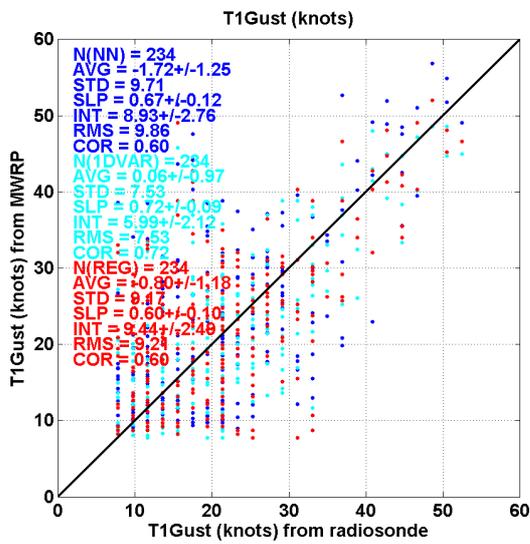
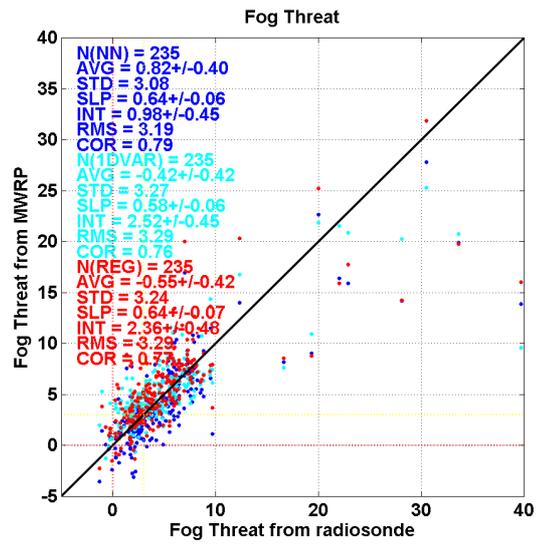
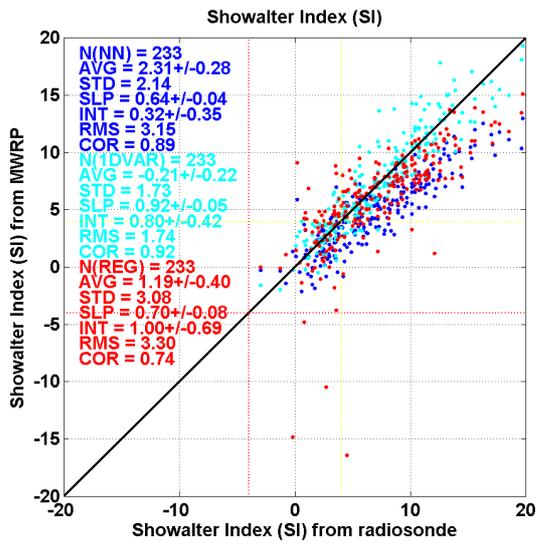


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3 Figure 10: As in Figure 9, but for (clockwise from top-left panel) Total Totals, STT, KO,  
 4 Lifted Index. Dotted yellow and red lines indicate thresholds for moderate and high potential,  
 5 respectively (where applicable).

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3 Figure 11: As in Figure 9, but for (clockwise from top-left panel) Showalter Index, Fog  
 4 Threat, T1 Gust, and Jefferson Index. Dotted yellow and red lines indicate thresholds for  
 5 moderate and high potential, respectively (where applicable).

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