

Pulsed Doppler lidar instruments

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Outline of Presentation

- Description of instruments, recent improvements and options
- Examples of data products
- Post processing of raw data
- Summary

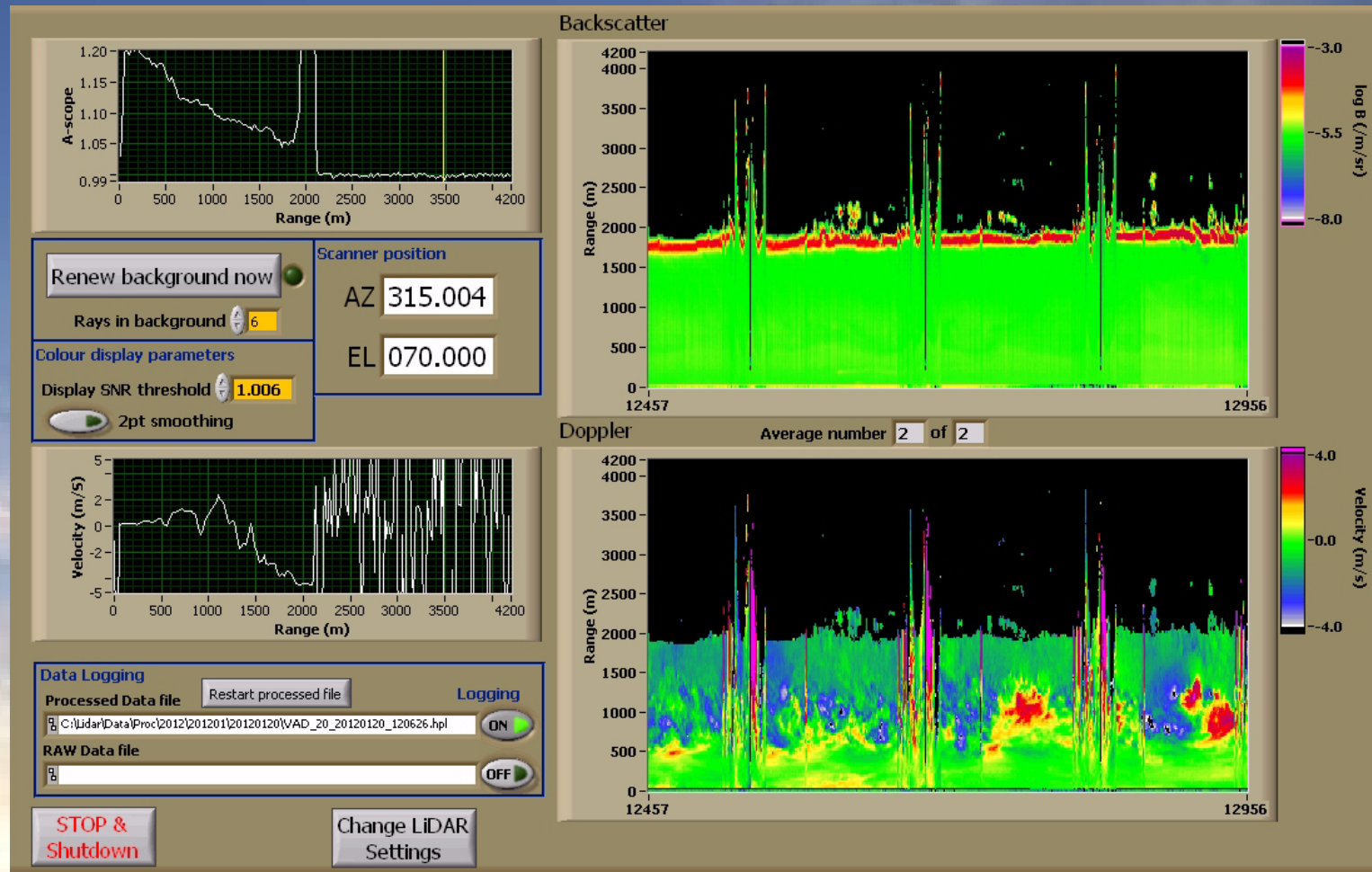
Description of instruments (1)

Stream Line^{Pro}

- Internal scanner which gives access to a conical field-of-regard optimised for profiling in the boundary layer and lower troposphere.
- Real-time data processing to 12km is available with a 100% duty cycle.
- Pro-XR: Increased performance
- Flexible software allows profiling to be achieved with a variety of scan geometries, scan sequences and temporal resolutions.
- Power consumption: 130W 24V DC (+340W at 50°C)
- Pro-Lite: Lower power version available if power limited (80W)
- Environmental: -20 to 50°C
- Weight: 65Kg
- Dimensions: 60x53x40cm
- New improved heated blower
- Autonomous, Rugged and Eye-safe: Class 1M

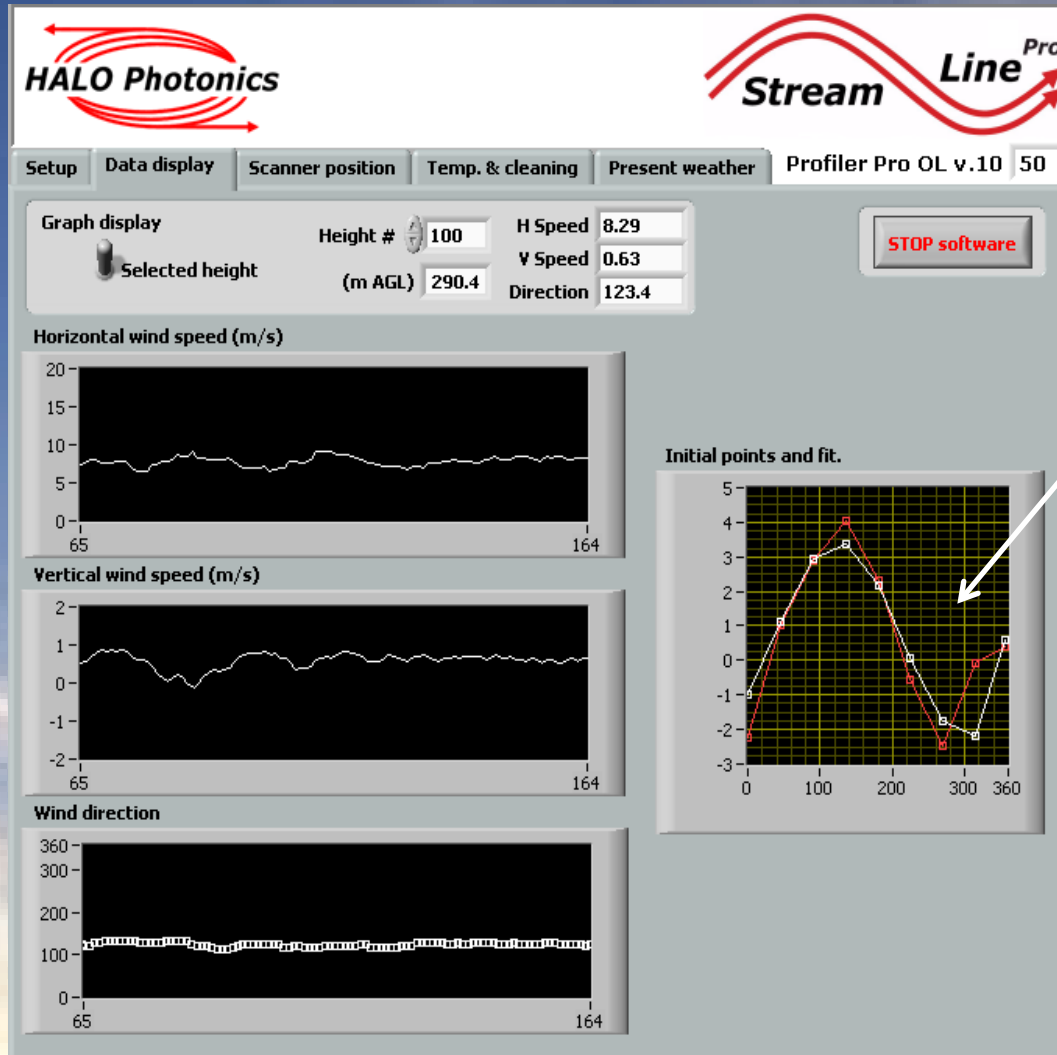


Real time display (visualisation mode)



Vertical stares with periodic wind profiles

Real time display (virtual mast mode)

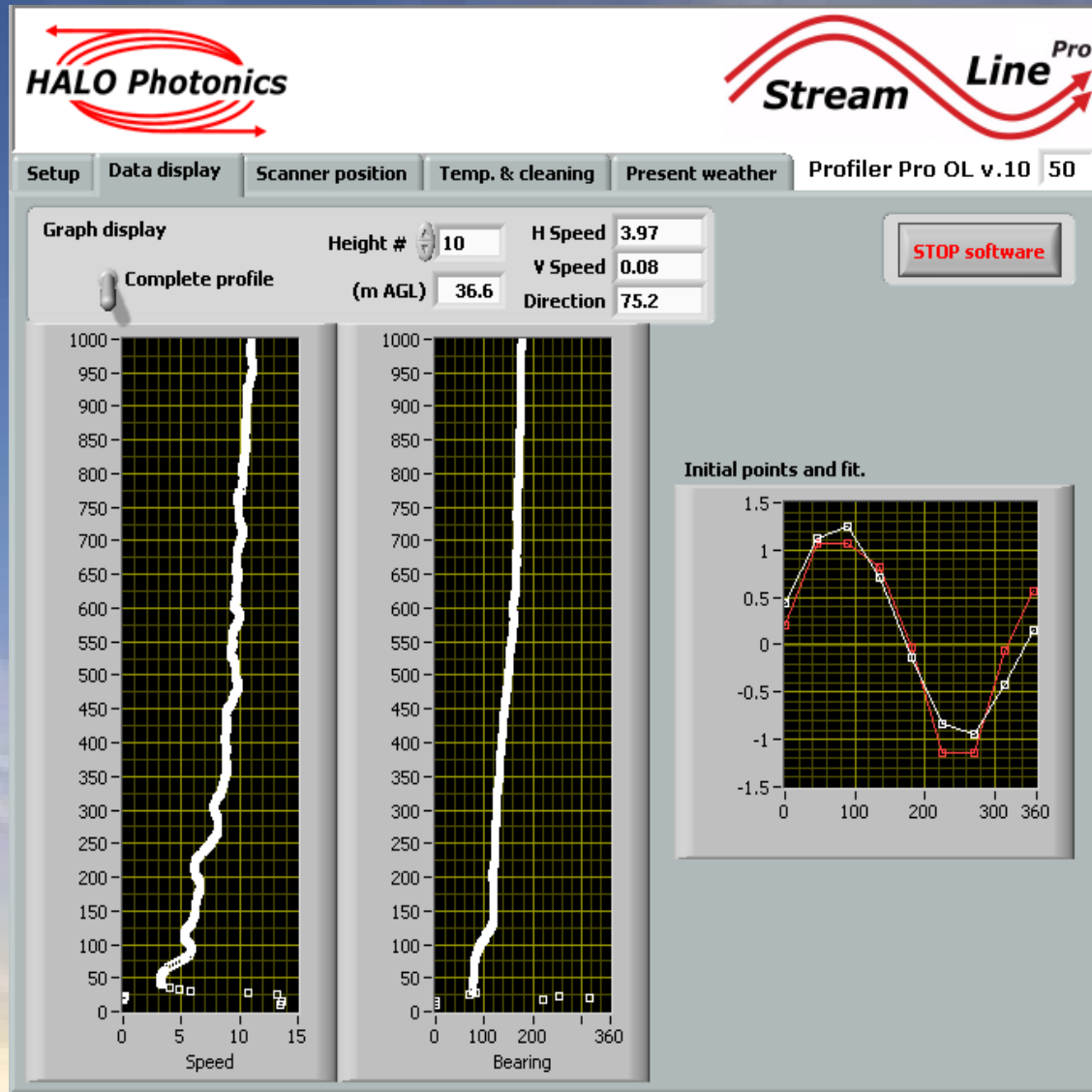


The number of rays and the scan geometry are variable.

Matrix inversion for u, v & w

A screen shot from the continuous profiling mode showing time histories of horizontal & vertical wind speed and bearing for a selected height

Real time display (virtual mast mode)



Boundary layer wind profiles at 2.6m height resolution
every few seconds

Description of instruments (2)

Stream Line^{XR}

- New compact version of the Stream Line pulsed Doppler lidar with an all-sky scanner
- Enclosure 25% smaller
- Extended range using more powerful transmitter
- New high performance signal processor
- Scan queue synchronised to GPS time
- Step-stare and continuous scanning
- Unlimited daily schedule
- Feedback scanning
- Full control of scanner parameters
- Overlapped range gates
- Raw data storage

- Mass approximately 85Kg
- Enclosure dimensions: 630 x 530 x 400mm
- Power requirement: 24V DC, 150W
- Extra 340 W for enhanced active cooling option for 50°C ambient temperatures



Stream Line^{XR} scan scheduler

As table or unlimited
daily sequence,
synchronised
to GPS time

Step-stare or
continuous scan

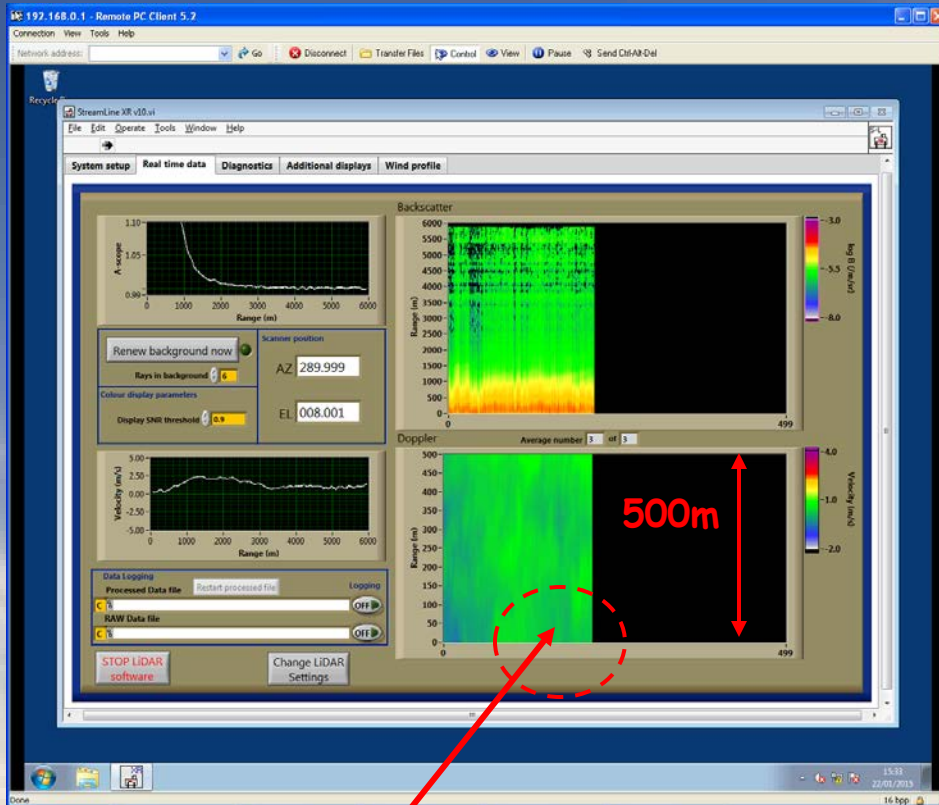
	Rays /pnt	No. Points	Repeat (min)	~Duration (min)	Focus
Stare	1				500m
VAD	1	4	10	0	500m
RHI	1	12	10	0	500m
Wind Profile (DBS)	1	3	30	0	500m
Scan file 1	1.5	2	5	0.17	500m
Scan file 2	1	1	5	0	500m
Scan file 3	5	1	5	0	500m
Scan file 4	1	1	6	0	500m

Approximate duration for all scans 0.17

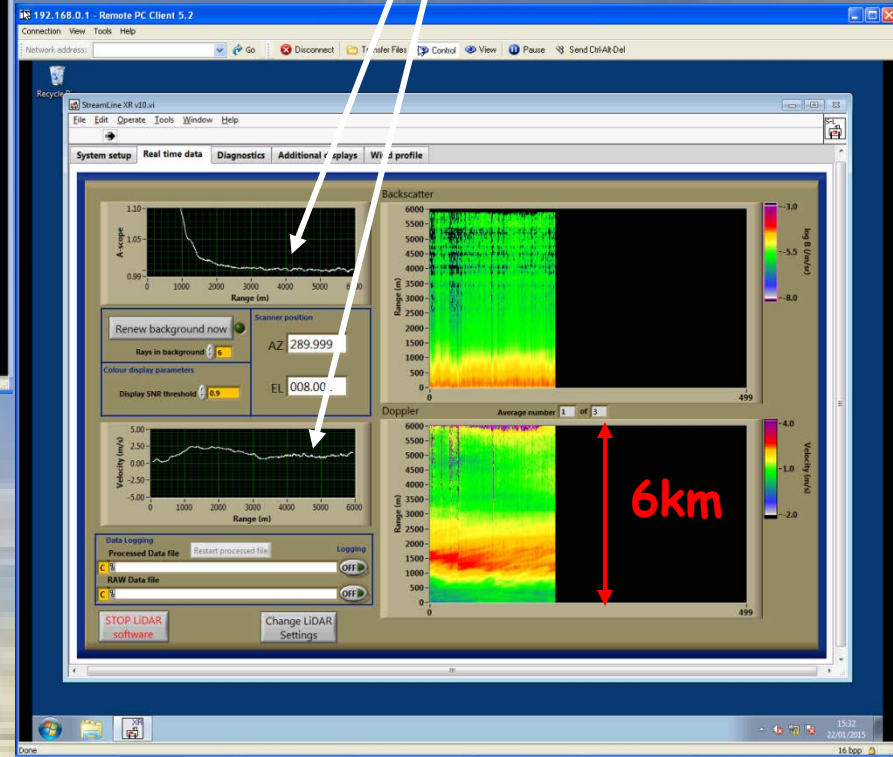
Update & close

Close without updating

Stream Line^{XR}

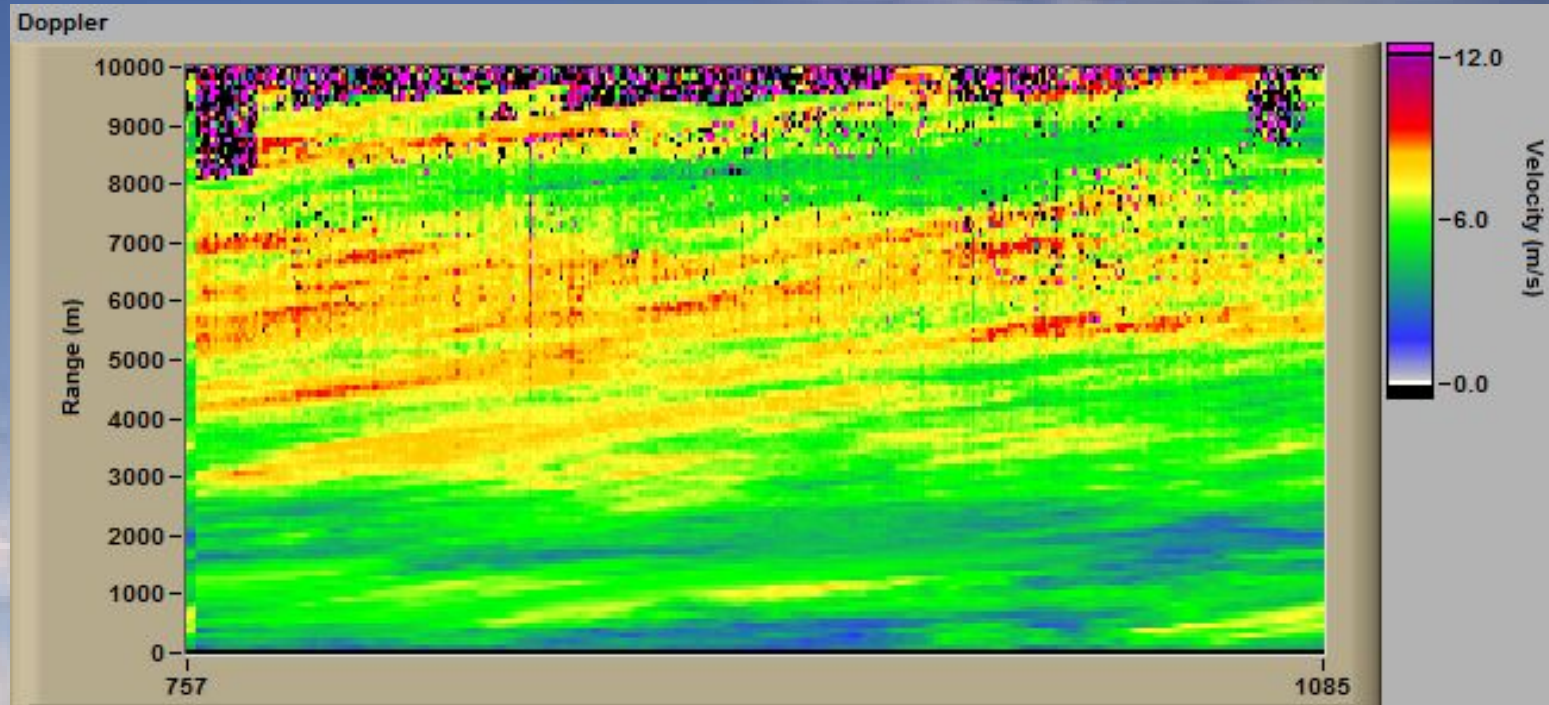


New signal processor
extracts good Doppler
estimates to lower SNR
(-31dB wideband)

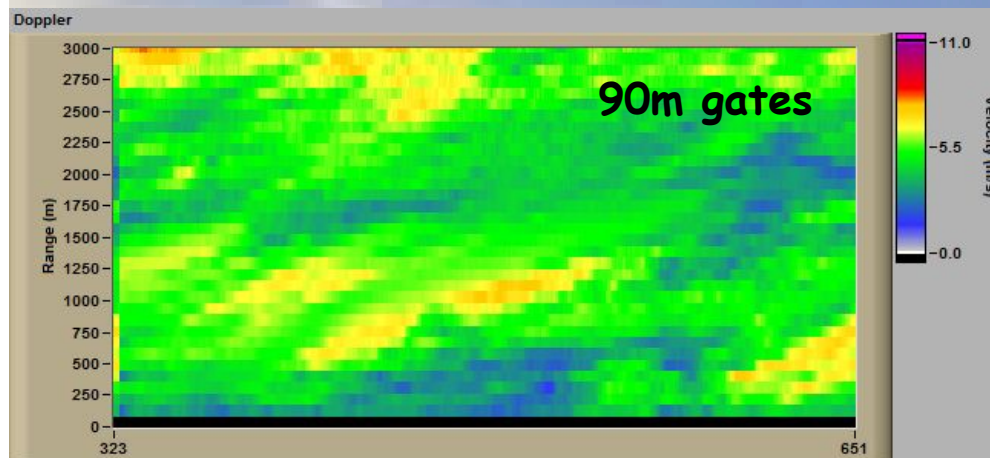
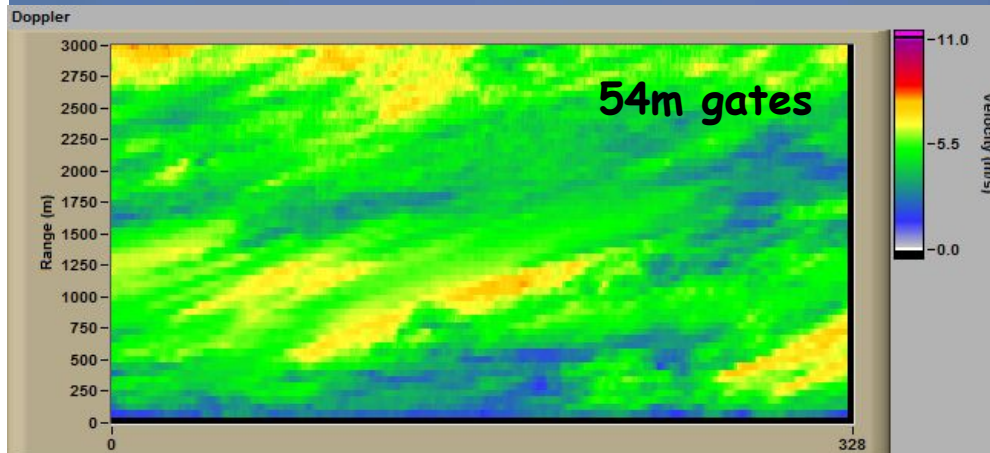
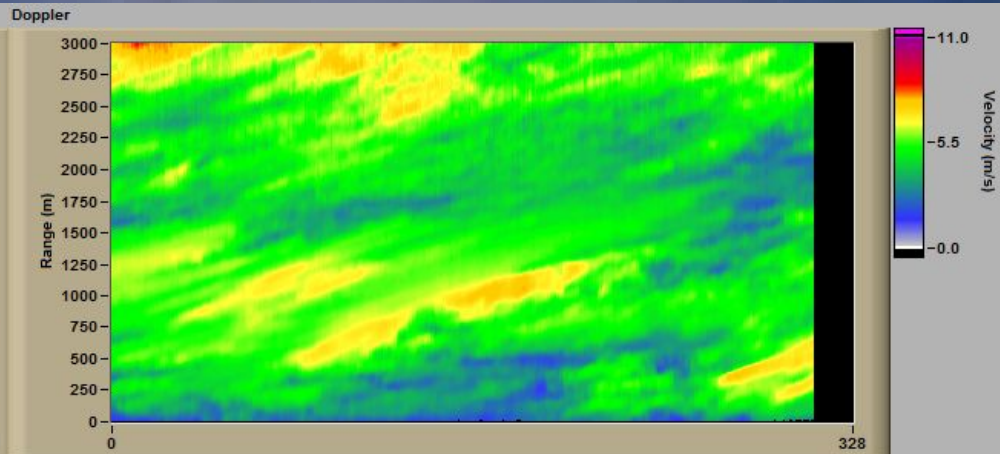
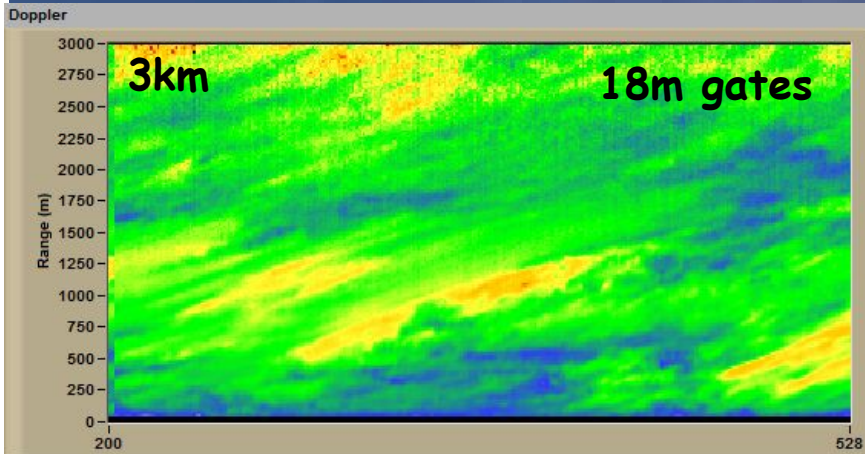


No blind zone, first usable
range gate is the first gate

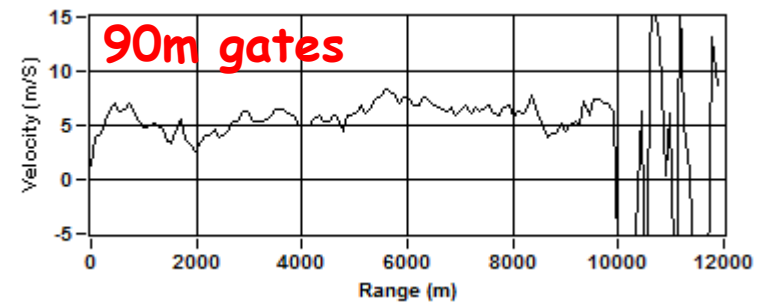
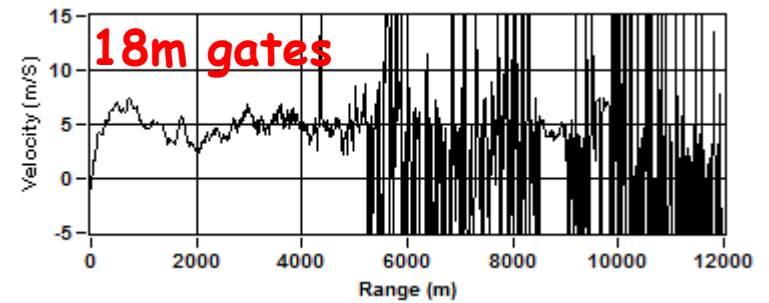
Illustration of post-processing raw data



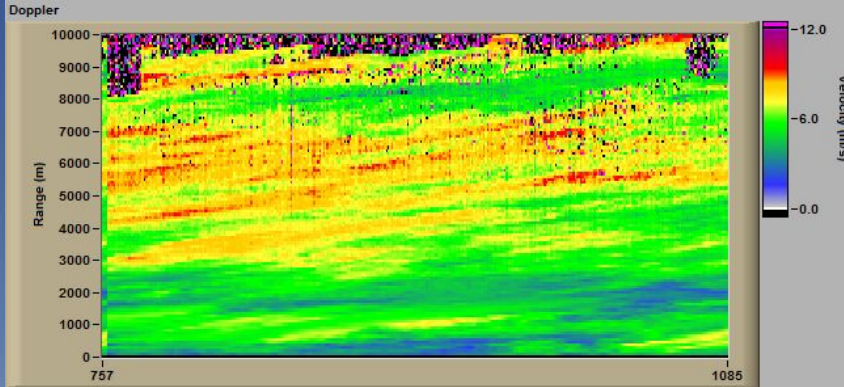
Range/time/Doppler plot for a fixed LOS
40m gates, 1 second average per ray, 6 minute record



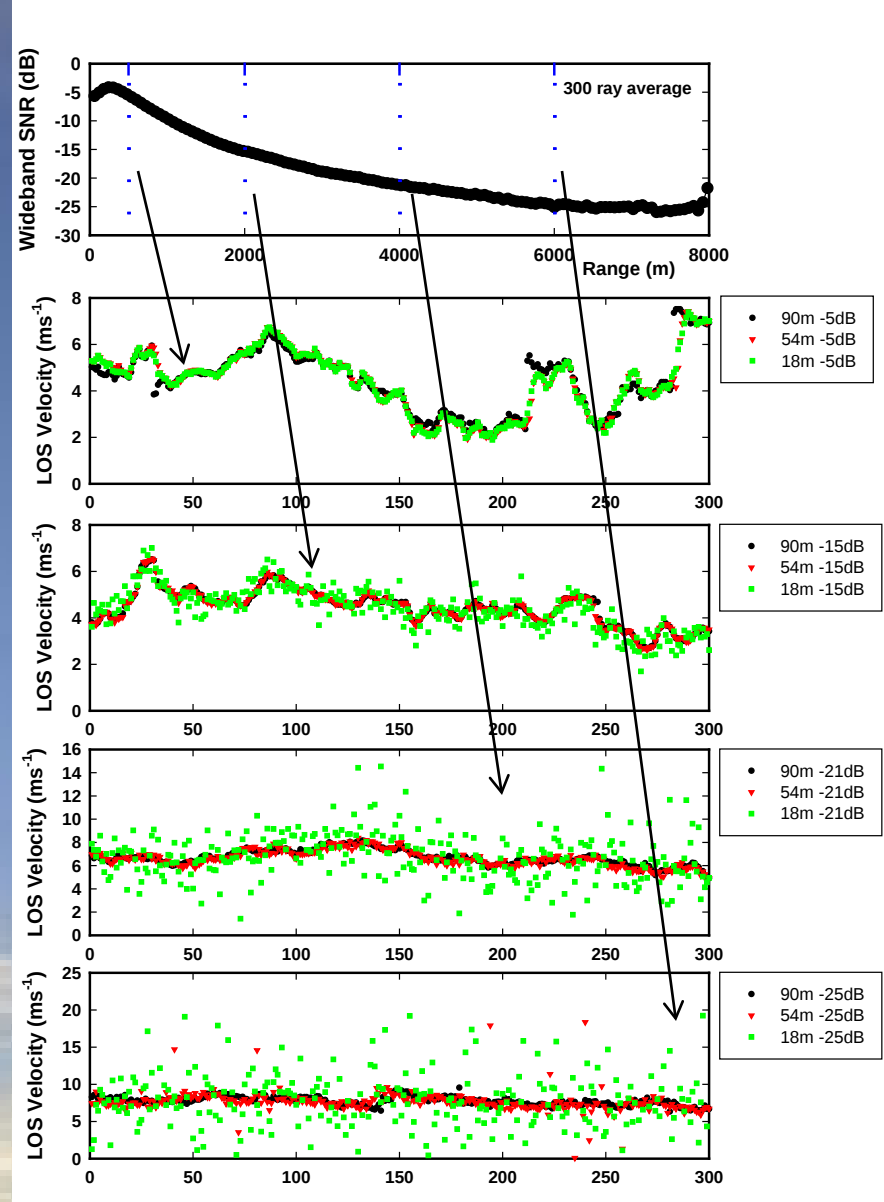
90m gates, 3m offset



Velocity estimates versus SNR and gate length



Atmospheric variability/lidar error



Error due to turbulence ?

- variability to turbulence is in a convective BL much larger than the Doppler error :

$$\overline{D_1 D_1}_{\text{obs}} = \overline{D_1 D_1}_{\text{turb}} + \Delta D^2 \approx \overline{D_1 D_1}_{\text{turb}}$$

=> accuracy of Doppler retrieval is not limiting factor

- Consider making *many* vast VAD scans with *fewer* points
- Determine covariance matrix of Dopplers

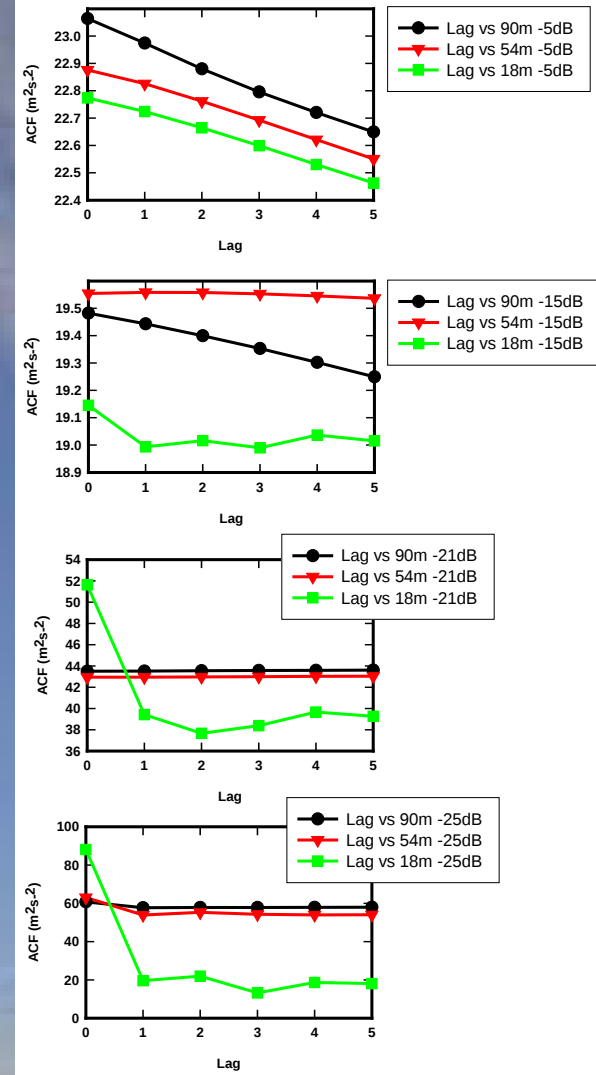
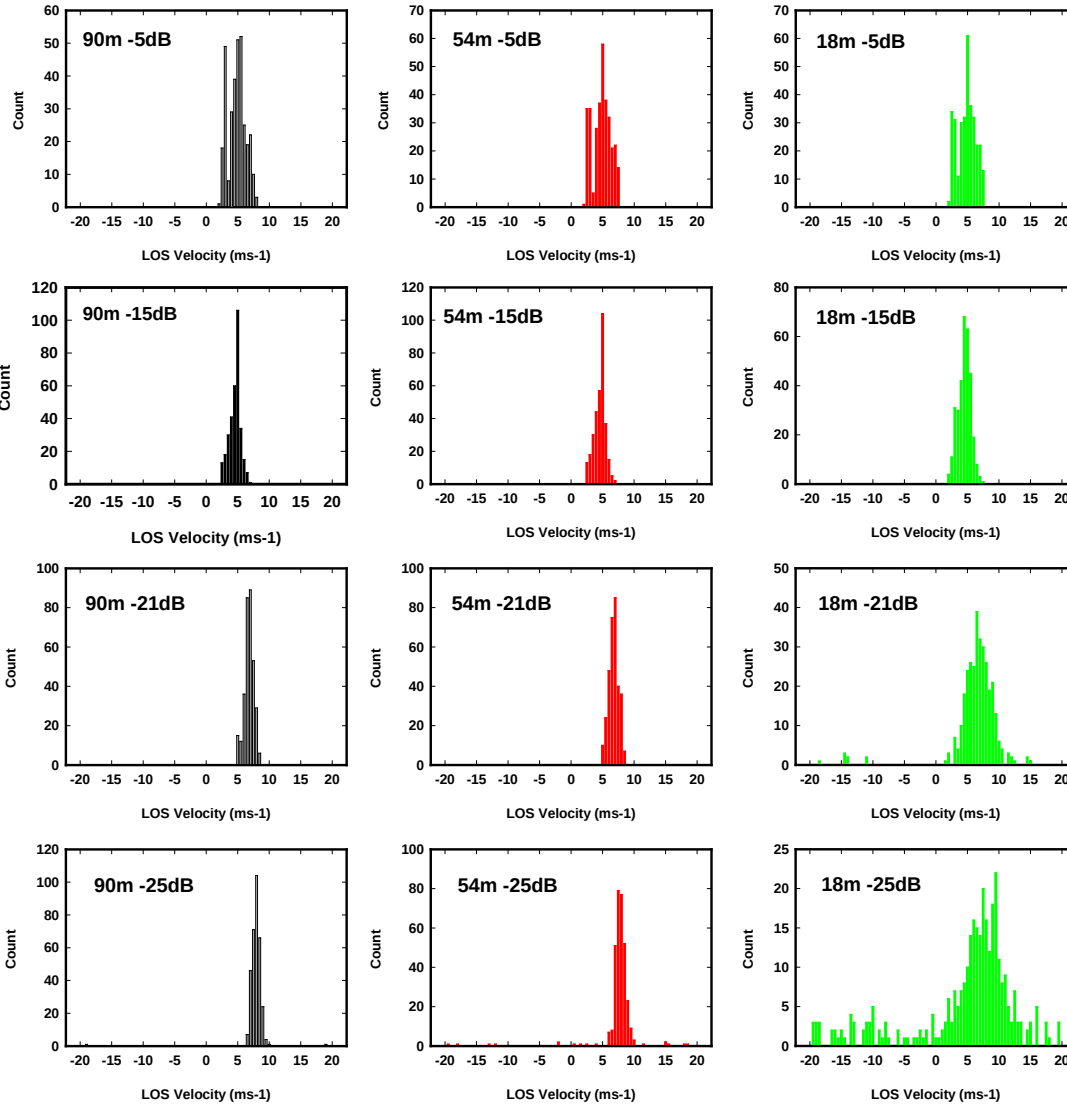
$$\overline{\overline{\sigma_D^2}} = \begin{pmatrix} \overline{D_1' D_1'} & \overline{D_1' D_2'} & \cdots \\ \overline{D_2' D_1'} & \overline{D_2' D_2'} & \cdots \\ \vdots & \vdots & \ddots \end{pmatrix}$$

- And calculate covariance matrix for Cartesian wind components

$$\overline{\overline{\sigma_v^2}} = \overline{\overline{M}} \cdot \overline{\overline{\sigma_D^2}} \cdot \overline{\overline{M}}^t = \begin{pmatrix} \sigma_{uu} & \sigma_{uv} & \sigma_{uw} \\ \sigma_{uv} & \sigma_{vv} & \sigma_{vw} \\ \sigma_{uw} & \sigma_{vw} & \sigma_{ww} \end{pmatrix}$$

- => Can we get enough VAD scans to ensure statistical

Velocity estimates versus SNR and gate length



Summary

- Two basic instrument concepts:
 - Profiling
 - All-sky scanning
- Recent upgrades:
 - High power transmitter
 - More powerful signal processor
 - Reduced size, weight & power consumption
 - More flexible scanning
 - Improved thermal characteristics
- New features offer greater scope for optimisation of performance