

# Latest Results from the RPG-FMCW-94-SP Cloud Radar

(or, to stay in line with WG-3:  
a few slides on a 89 GHz radiometer with some active  
94 GHz extensions to give the radiometer-derived LWP  
a bit more vertical structure...)

**Thomas Rose, Harald Czekala, Martin Philipp**



## 94 GHz FMCW Doppler Cloud Radar:

- Very High Sensitivity (down to -60 dBz)
- High Dynamic Range (-60 to +20 dBz)
- Complete Rain Mitigation System
- Compact and Low Cost
- Full Networking Capability (TCP/IP)

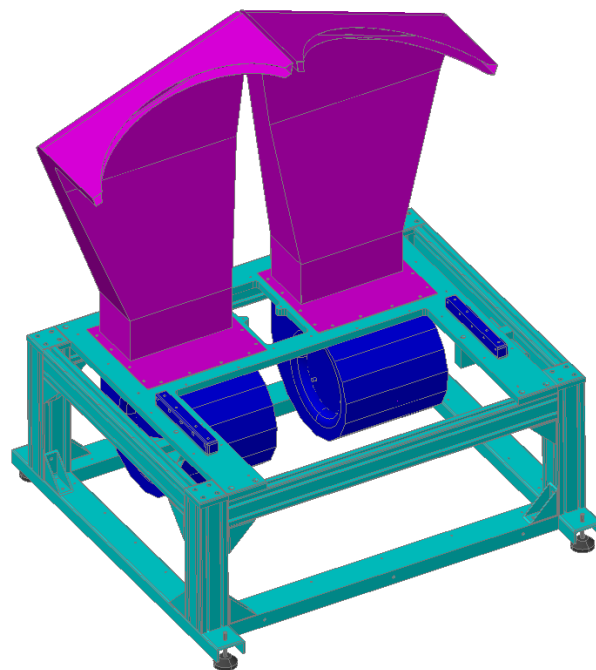
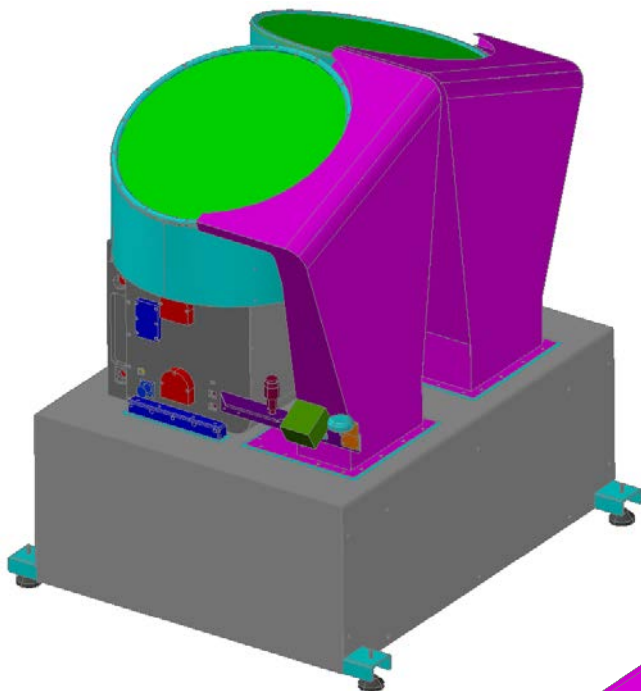
Includes 89 GHz Channel for Measurement of:

**Integrated Liquid Water Path (LWP)**



Parameter	Specification
Centre Frequency	94 GHz ( $\lambda=3.19$ mm) $\pm$ 100 MHz typical, (adjustable by software between 92.3 and 95.7 GHz)
IF range	350 kHz to 3 MHz
Transmitter power	2 W typical (solid state amplifier) Lower transmitter powers are available for reduced priced
Antenna type	Bi-static Cassegrain with 500 mm aperture
Antenna gain	51.5 dB
Beam width	0.48° FWHM
Polarisation	V (optional V & H)
Rx System Noise Figure	4 dB (400 K system noise temperature)
Typical Dynamic range (sensitivity) with 2 W transmitter	-60 dBz to +20 dBz (at 500 m height / 5 m resolution) -50 dBz to +20 dBz (at 2 km height / 10 m resolution) -47 dBz to +20 dBz (at 4 km height / 30 m resolution) -36 dBz to +20 dBz (at 10 km height / 30 m resolution)
Ranging	100 m to 12 km typical, 16 km maximum
Maximum vertical resolution	1 m (range: 0.1 km – 0.6 km), 2 m (range: 0.6 km – 1.0 km), 4 m (range: 1.0 km – 2.5 km), 8 m (range: 2.5 km – 5.0 km), 16 m (range: 5.0 km – 12.0 km)
Calibrations (automatic)	Power monitoring of the transmitter, plus receiver Dicke-switch for gain drift compensation (radar and passive channel)
Calibrations (maintenance)	Liquid nitrogen receiver calibration, external reference sphere

<b>A/D Sampling rate</b>	<b>8.2 MHz (data processing between 0.35 and 3 MHz)</b>
<b>Data processing system</b>	High-Performance embedded PC
<b>Sampling rate (full profiles)</b>	Adjustable: $\geq 1$ second
<b>Doppler range</b>	$\pm 9$ m/s unambiguous velocity range (0-2500 m), $\pm 4.2$ m/s above
<b>Doppler resolution</b>	$\pm 1.5$ cm/s or higher
<b>Chirp variations</b>	3 typical, 10 possible, re-programmable
<b>Passive channels</b>	89 GHz for integral LWP detection
<b>Control connection</b>	TCP/IP connectivity via fibre optics data cable to internal PC
<b>Operation software</b>	Real time visualization, real time data extraction, real time control (adaptive observation modes depending on context)
<b>Data products (available as files)</b>	Reflectivity, Doppler spectra (including calculated moments), LWC profiles. Data levels: L1: calibrated dBZ, L2: retrieved data
<b>Data formats</b>	netCDF (CF convention), proprietary binary, ASCII
<b>Mitigation system for rain/fog/dew</b>	Strong dew blower (approx. 2000 m <sup>3</sup> /h), radomes with hydrophobic coating ,optional heater (additional 2-4 kW)
<b>Additional sensors</b>	Automatic weather station with P, T, RH, RR, Snow, WS, WD
<b>Scanning / mounting</b>	Baseline: mounted on a fixed stand of 0.5 m height Optional: scanner unit for full sky scanning capability
<b>Dimensions</b>	115×56×82 cm <sup>3</sup> (with antennas), (80×40×40 cm <sup>3</sup> (box only)
<b>Weight</b>	Approx. 280 kg/80 kg with/without stand & blower (w/o scanner)



Ground based radar requires strong blower / heater:

The contamination of the microwave windows by snow, ice, rain leads to unacceptably high reflectivity errors or even ‚blindness‘ of the instrument

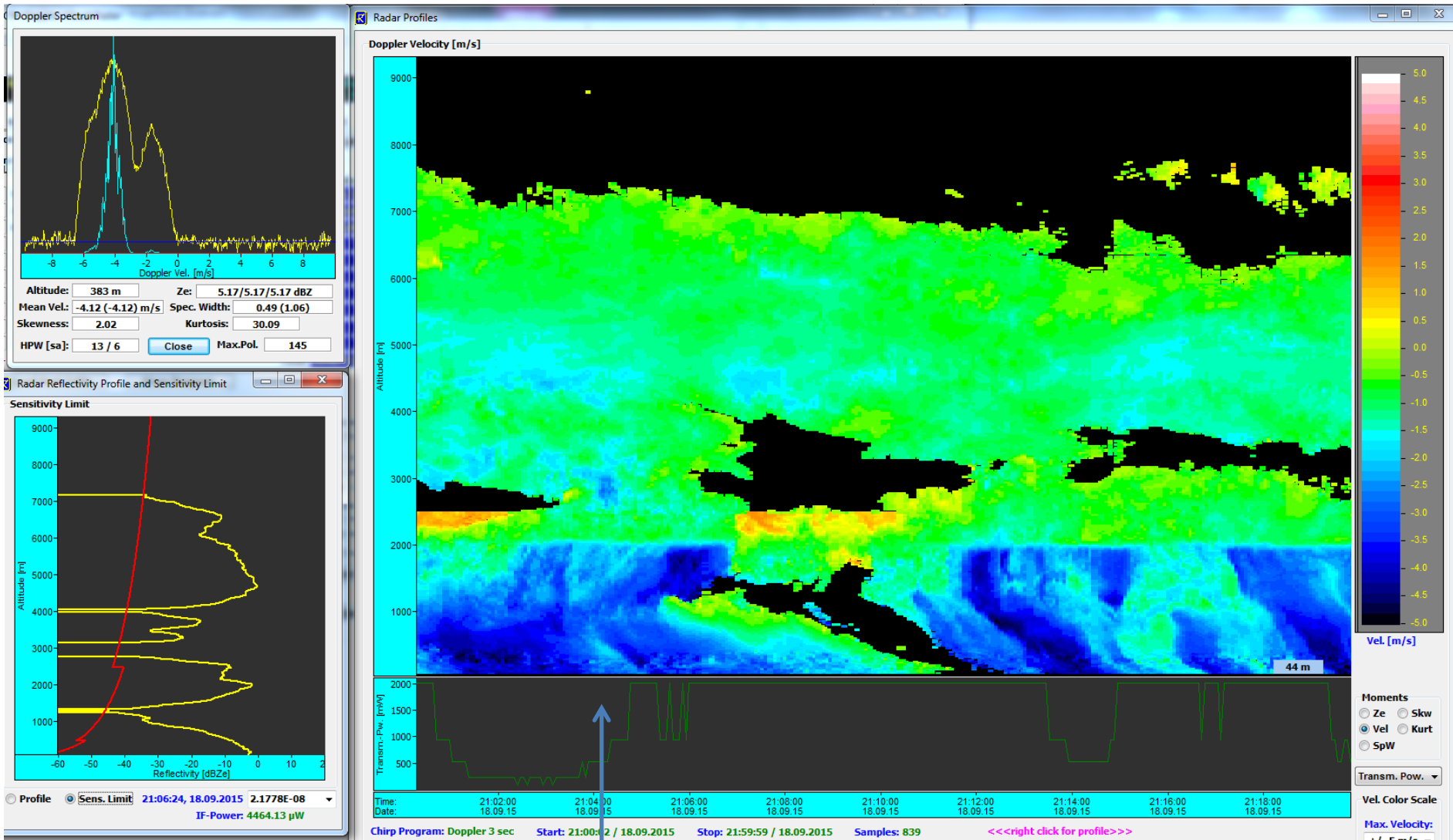
Even small contaminations with rain droplets, condensation or snow are causing big errors in LWP retrievals from the direct detection channel

Solution:

- Strong air flow of  $2 \times 2000 \text{ m}^3/\text{h}$  over the windows
- Air can optionally be heated. Power: 2 kW to 4 kW



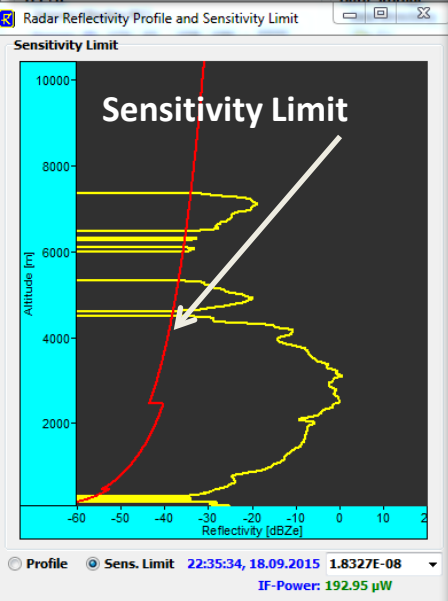
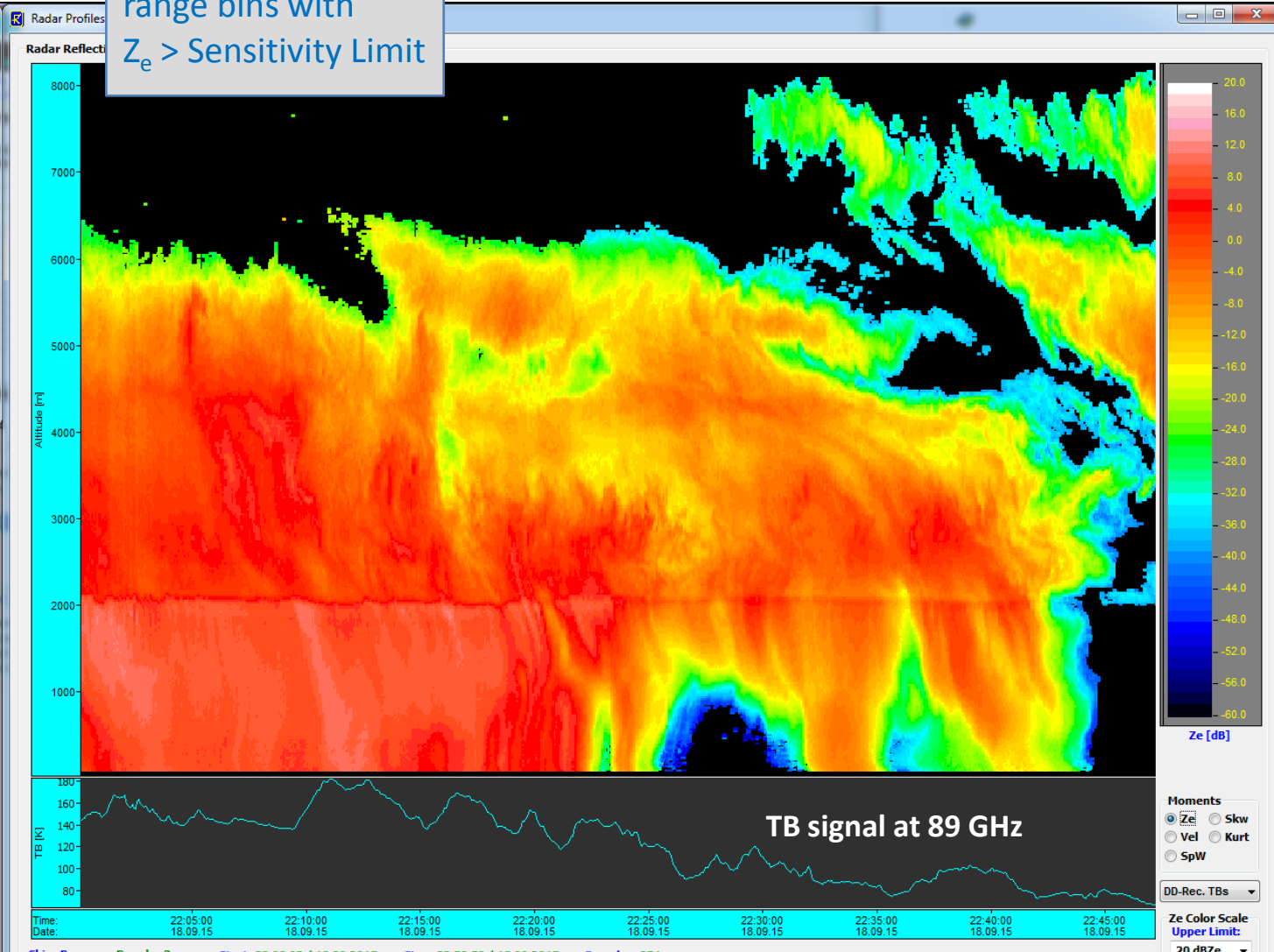
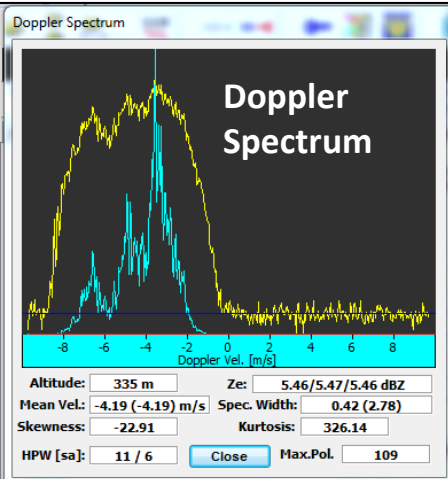
# Automatic Transmitter Power Tuning

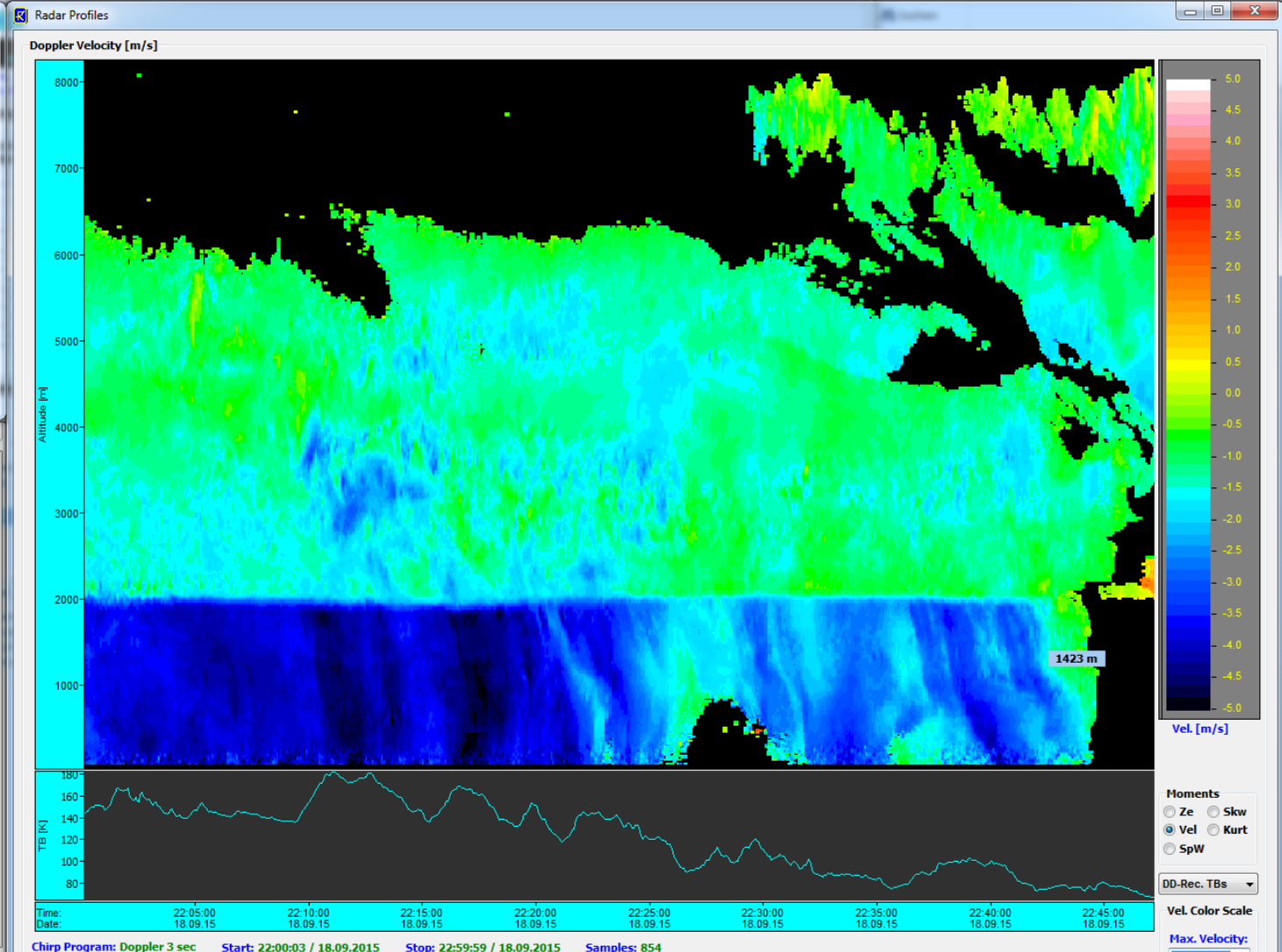
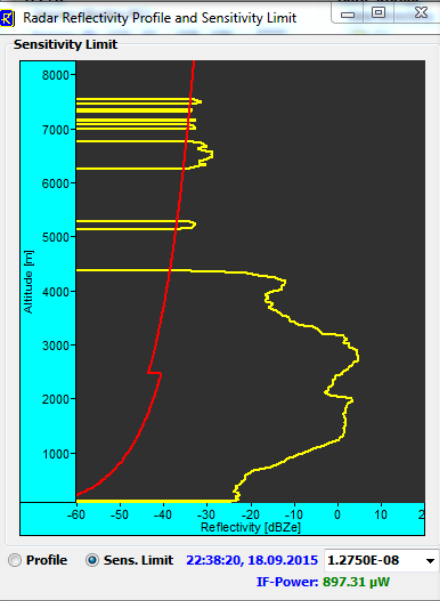
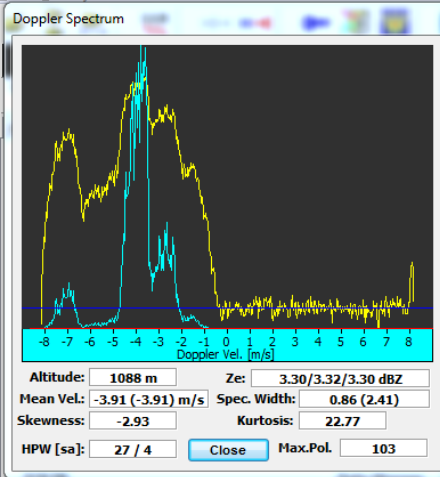


Transmitter Power Adjustments increase dynamic range by 16 dB!

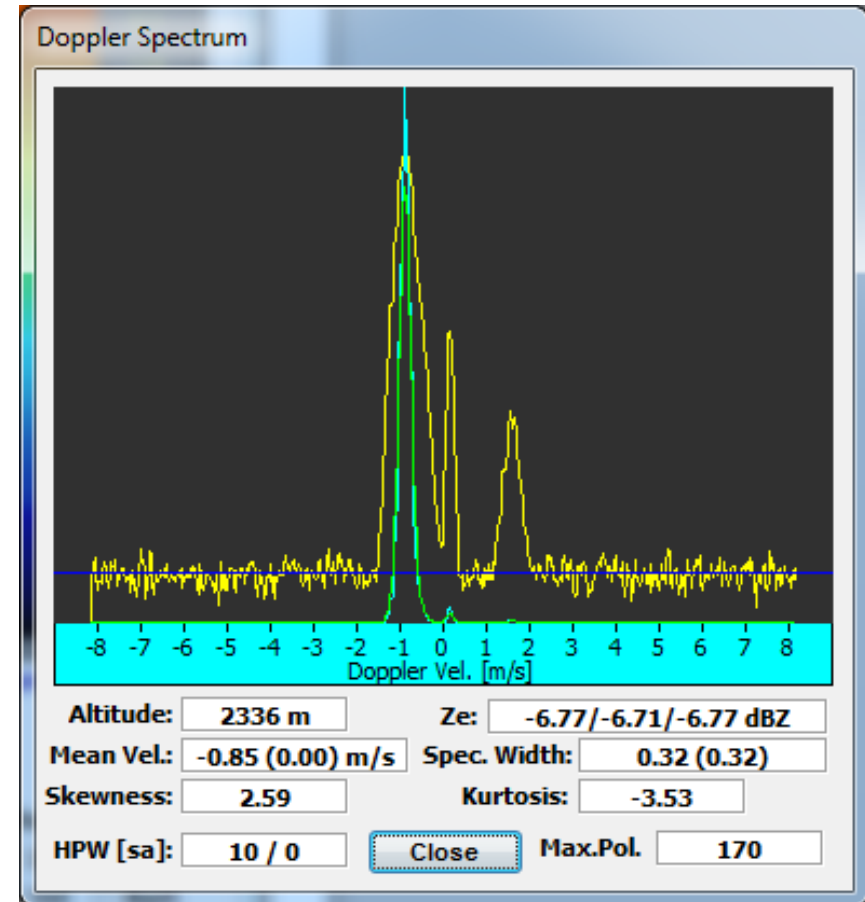
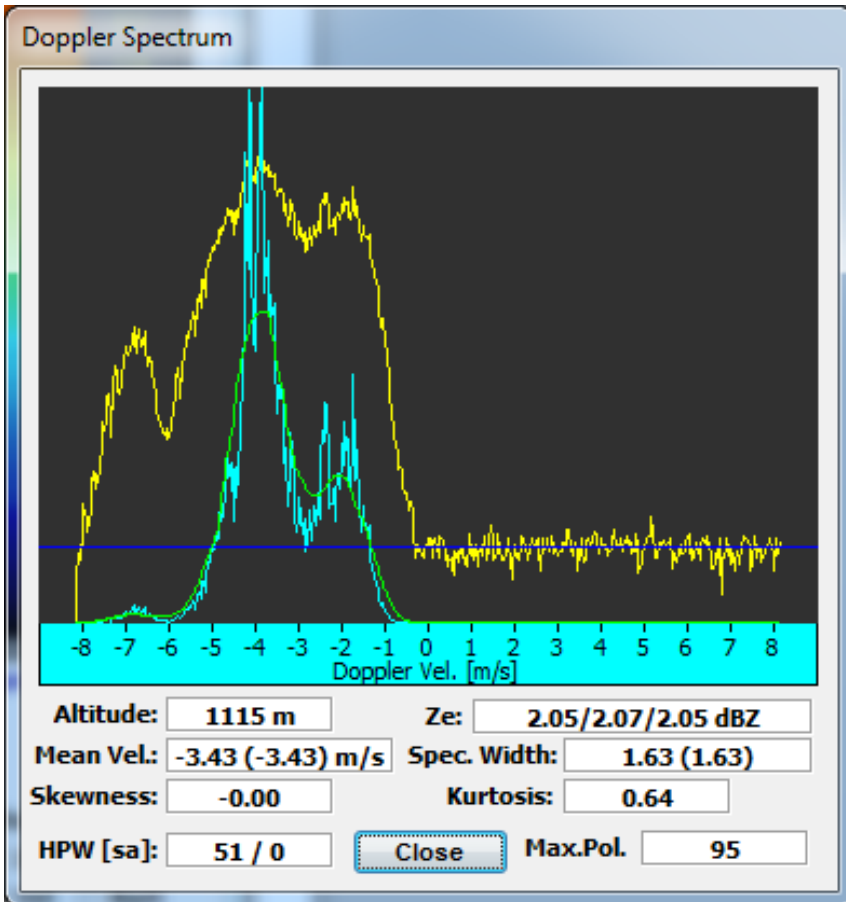
# High Radar Reflectivity Sensitivity

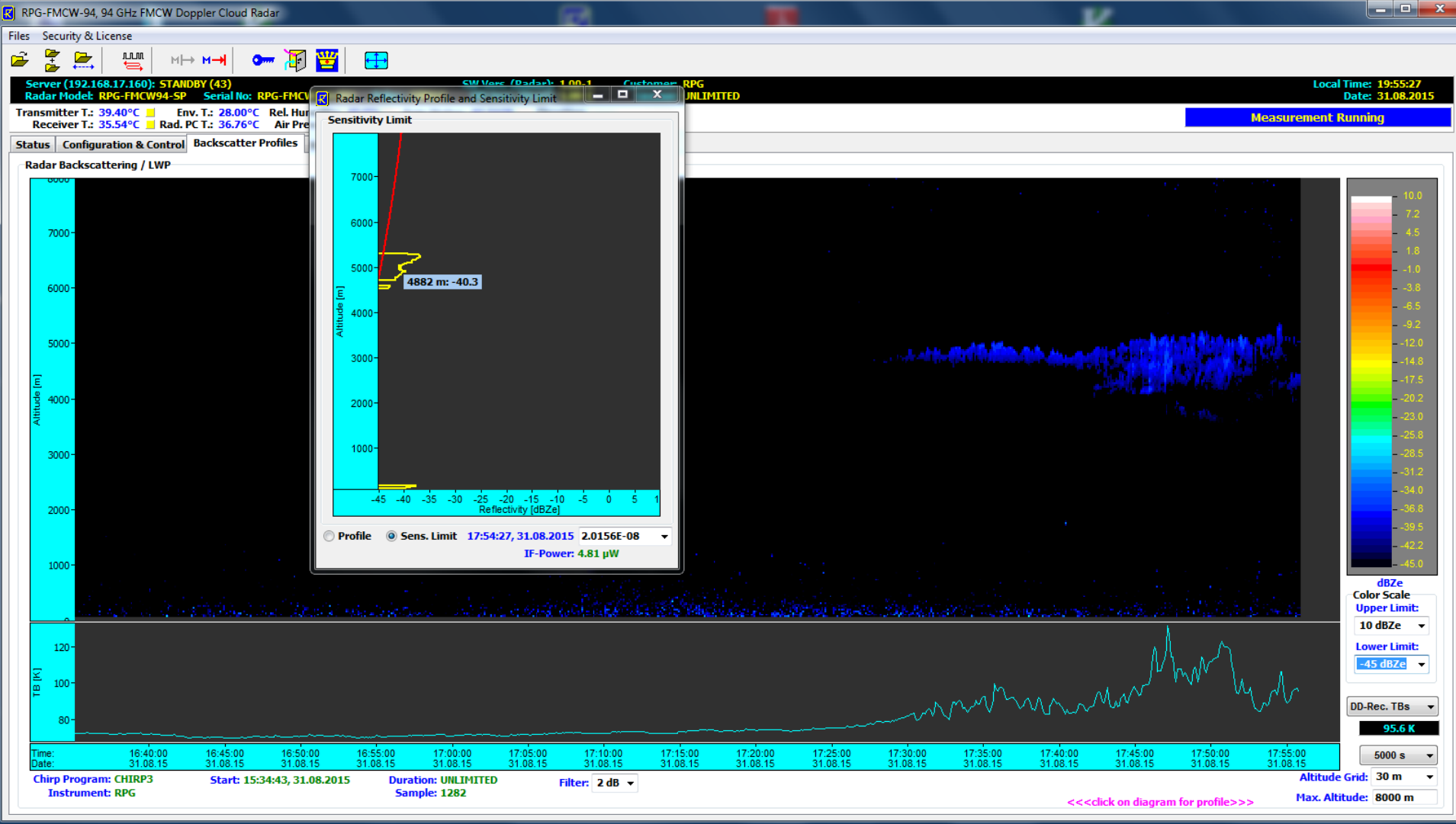
Doppler spectra are only calculated for range bins with  $Z_e > \text{Sensitivity Limit}$

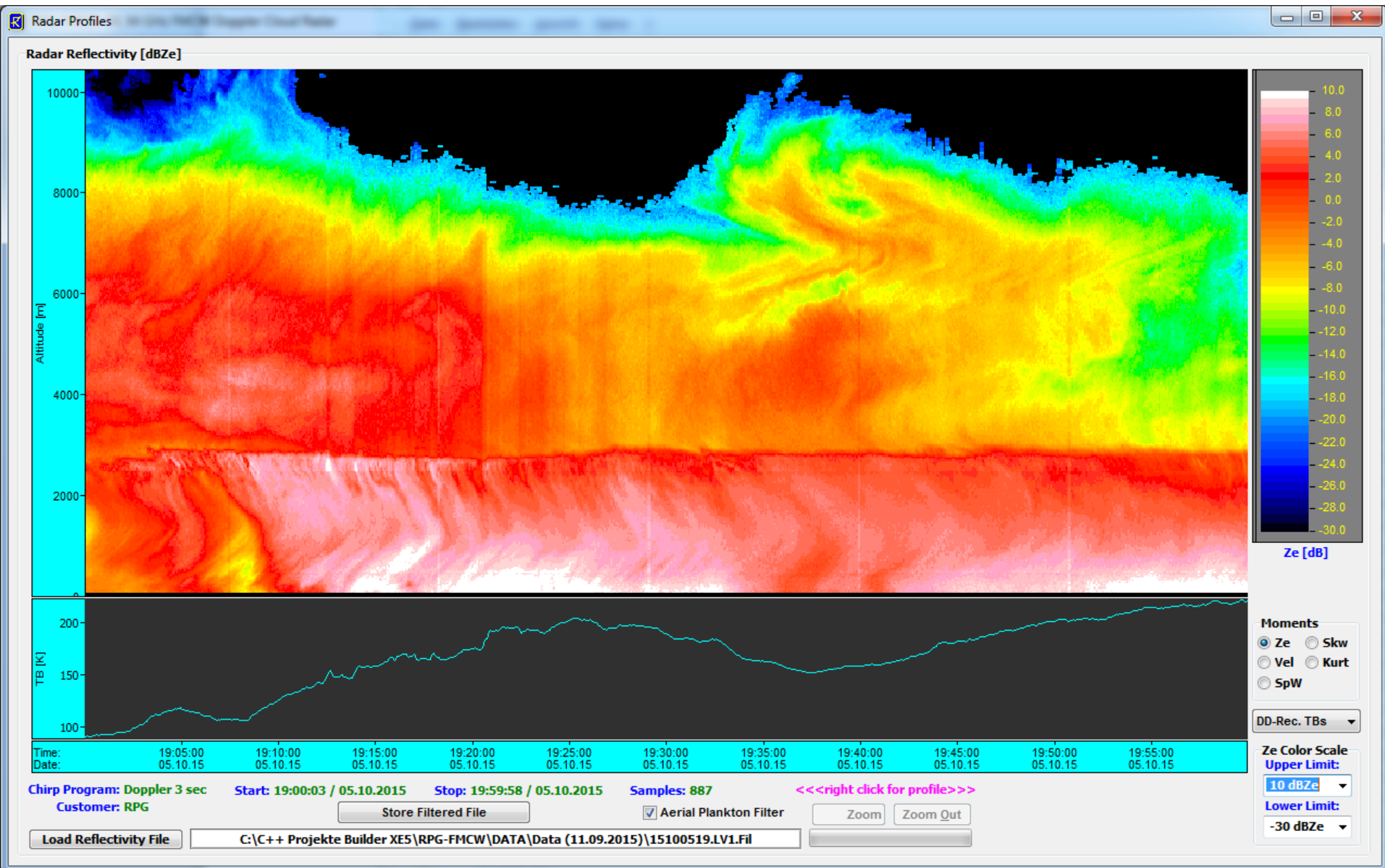


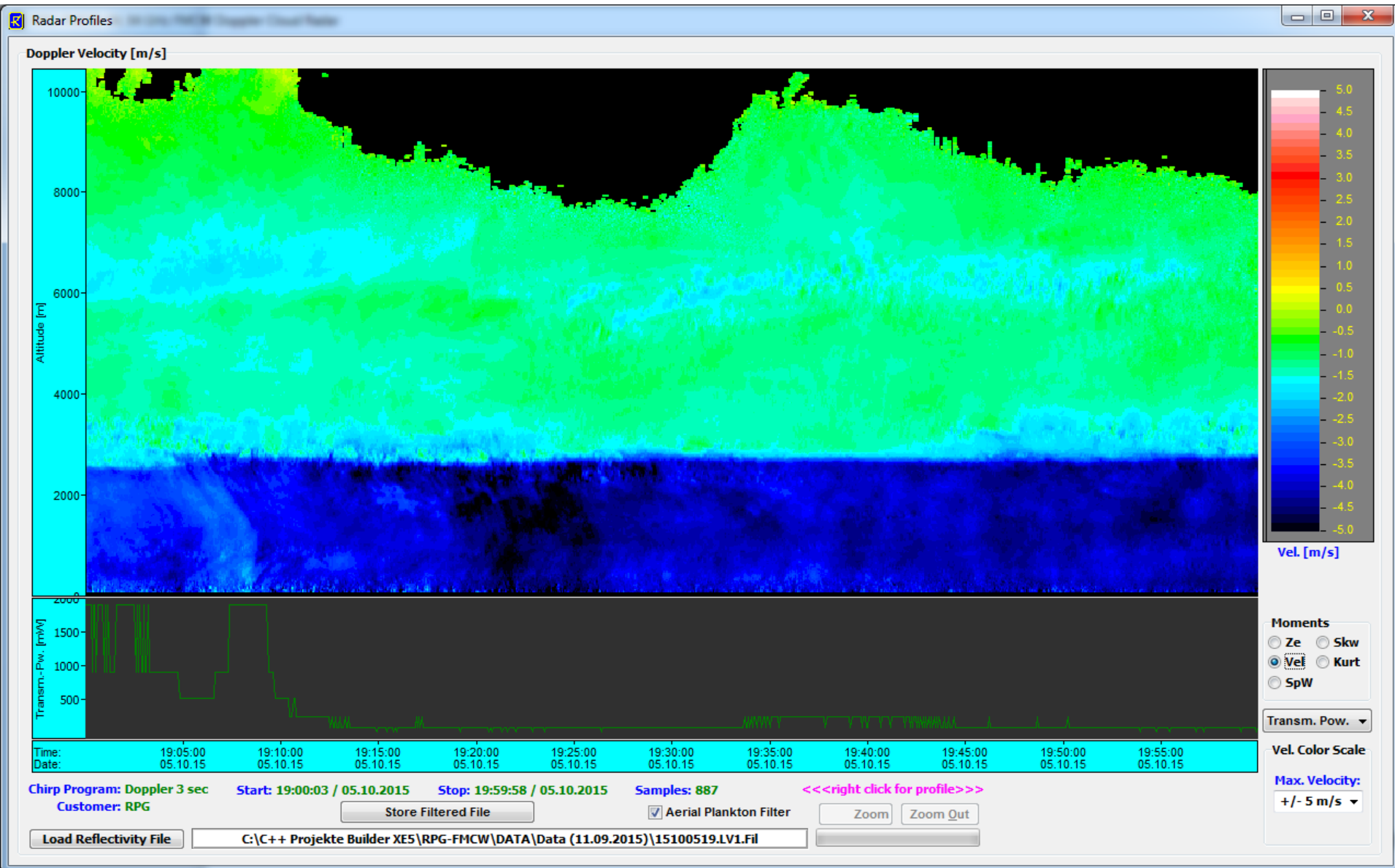


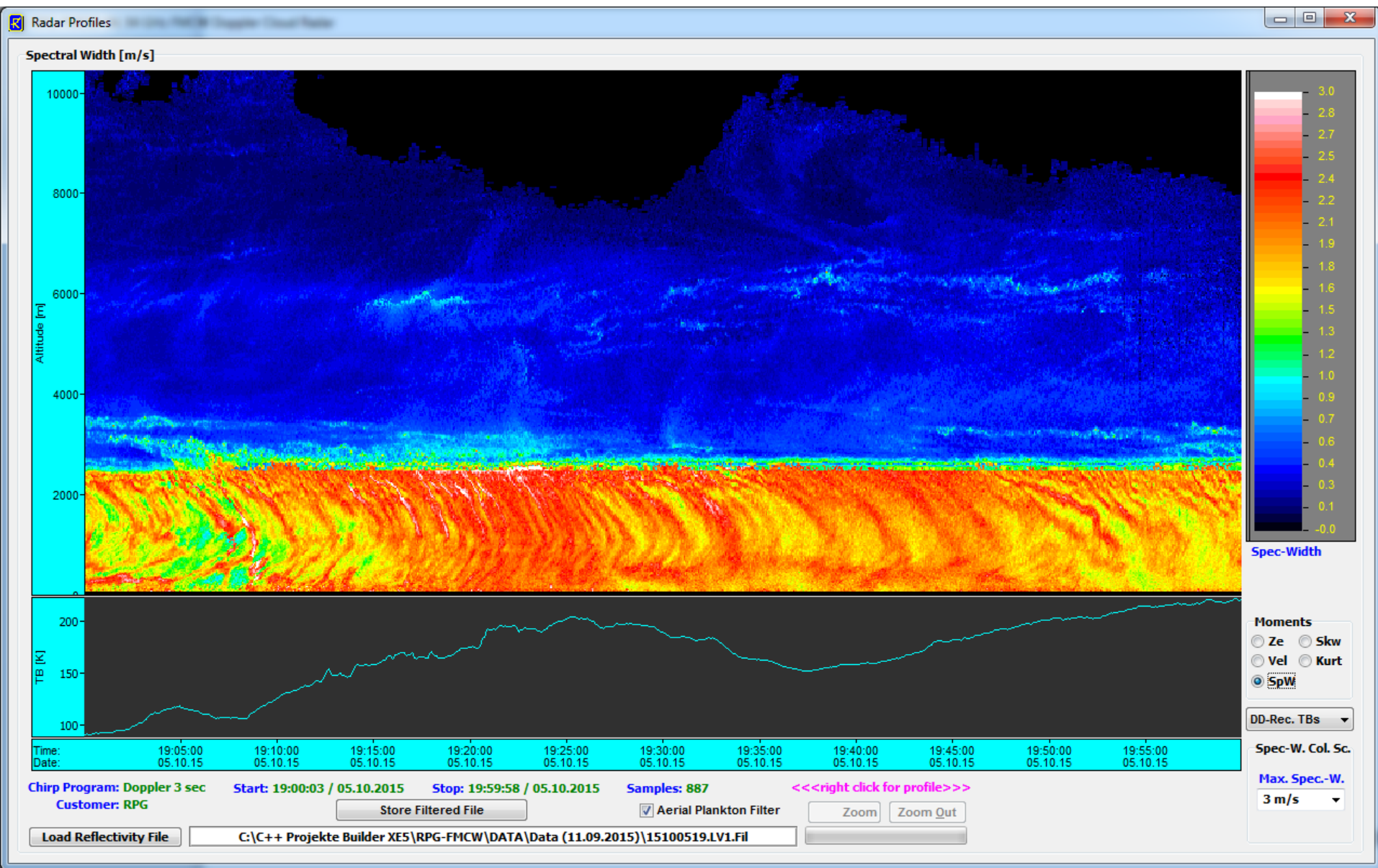




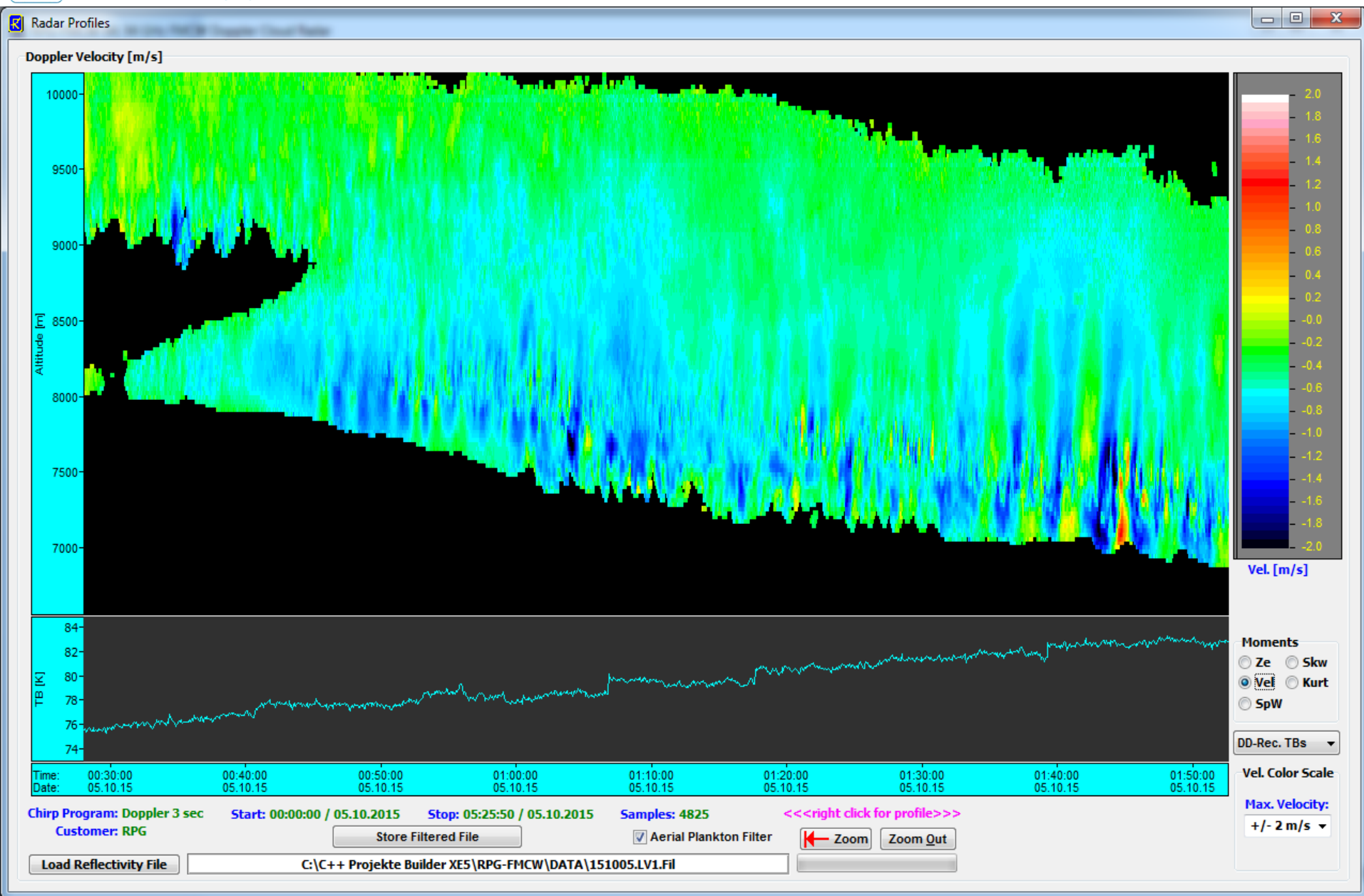


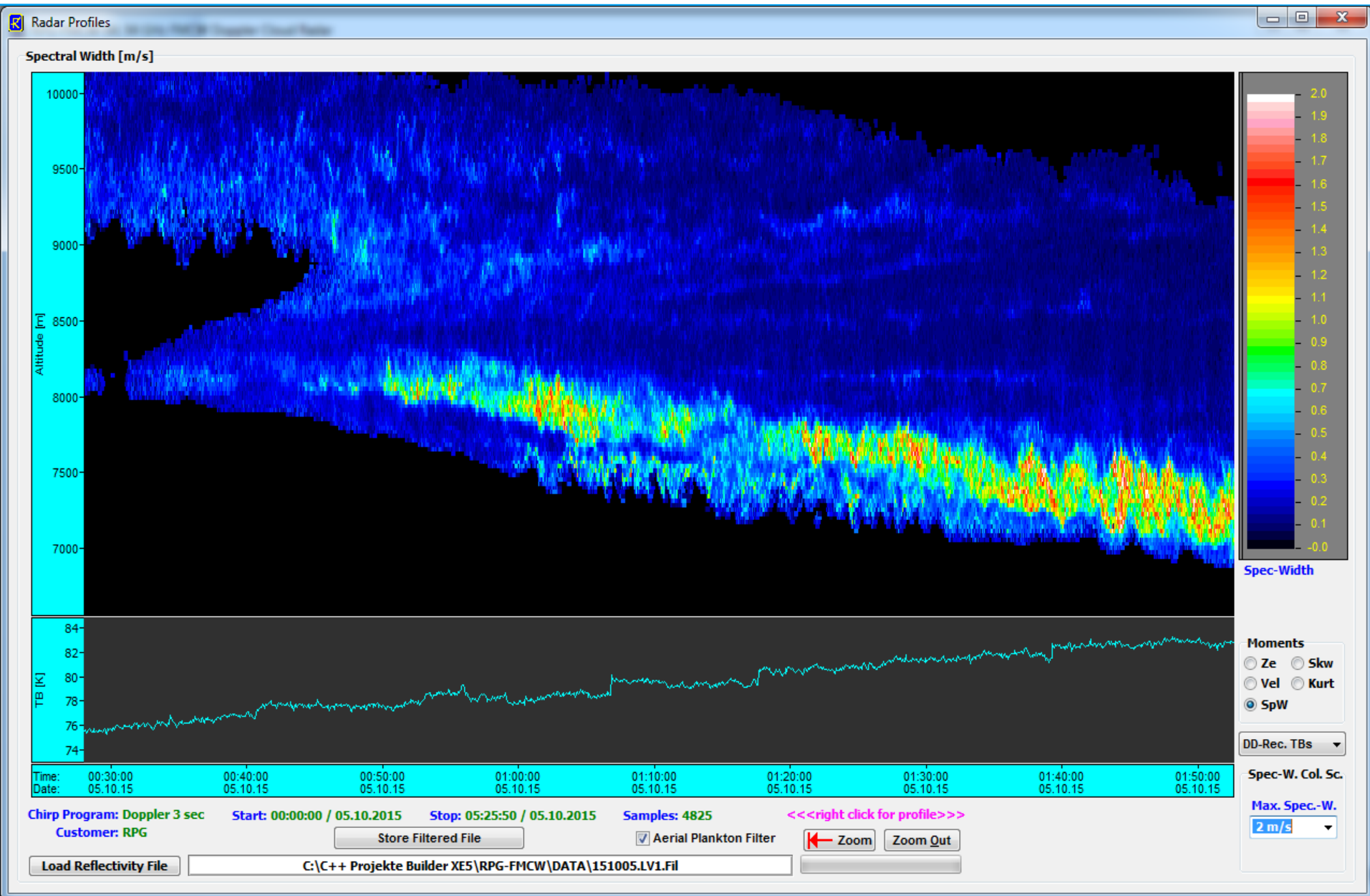




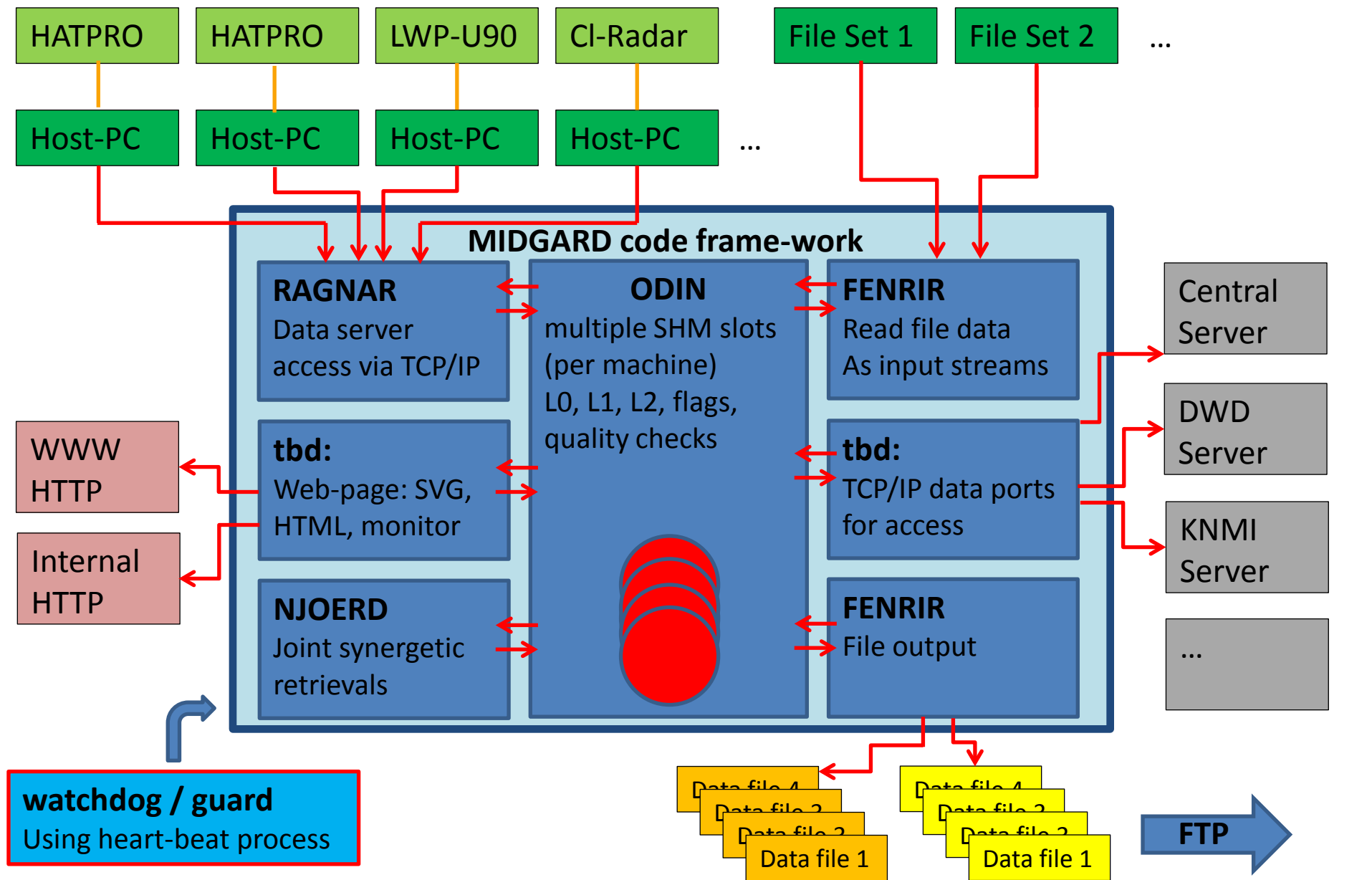




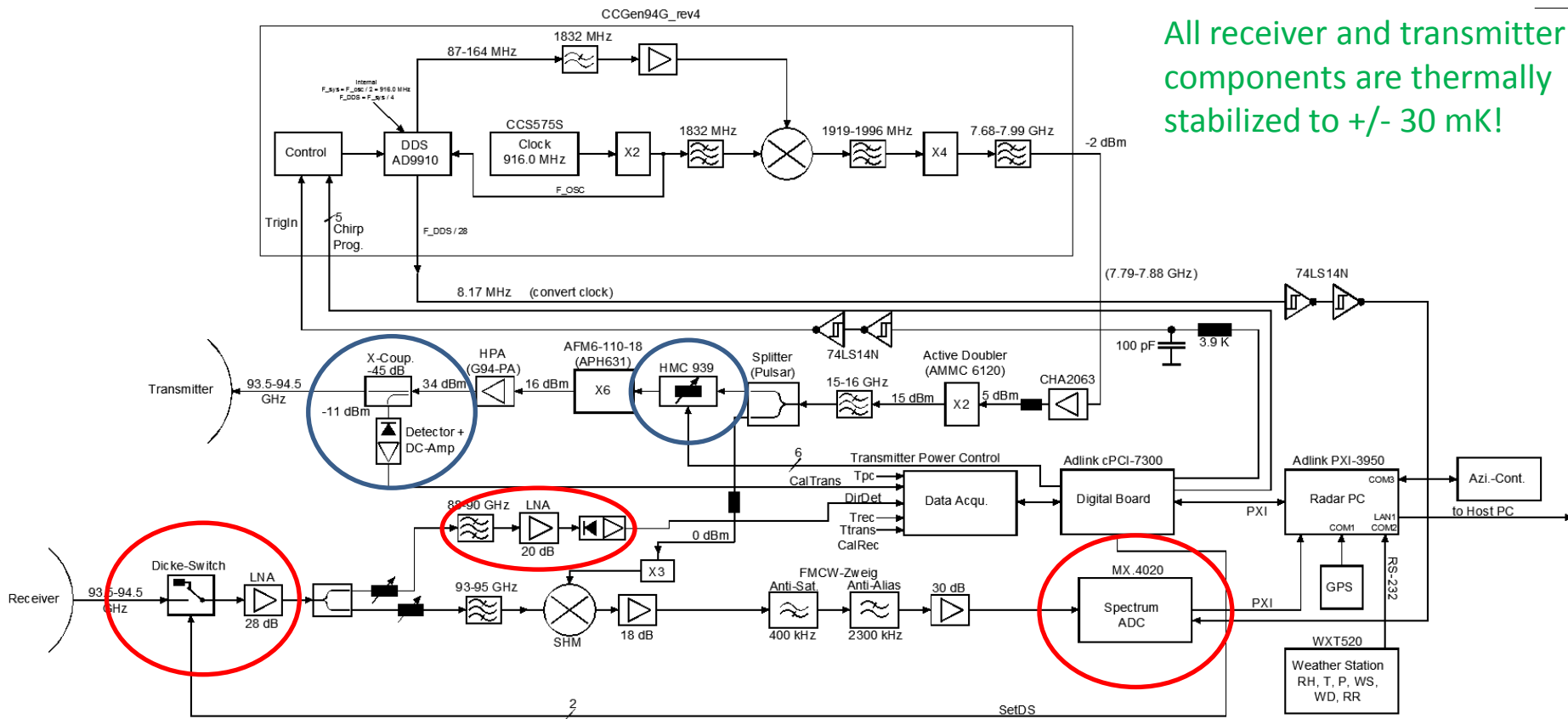




# Synergy with MWR: MIDGARD, ODIN, RAGNAR, ...



All receiver and transmitter components are thermally stabilized to +/- 30 mK!

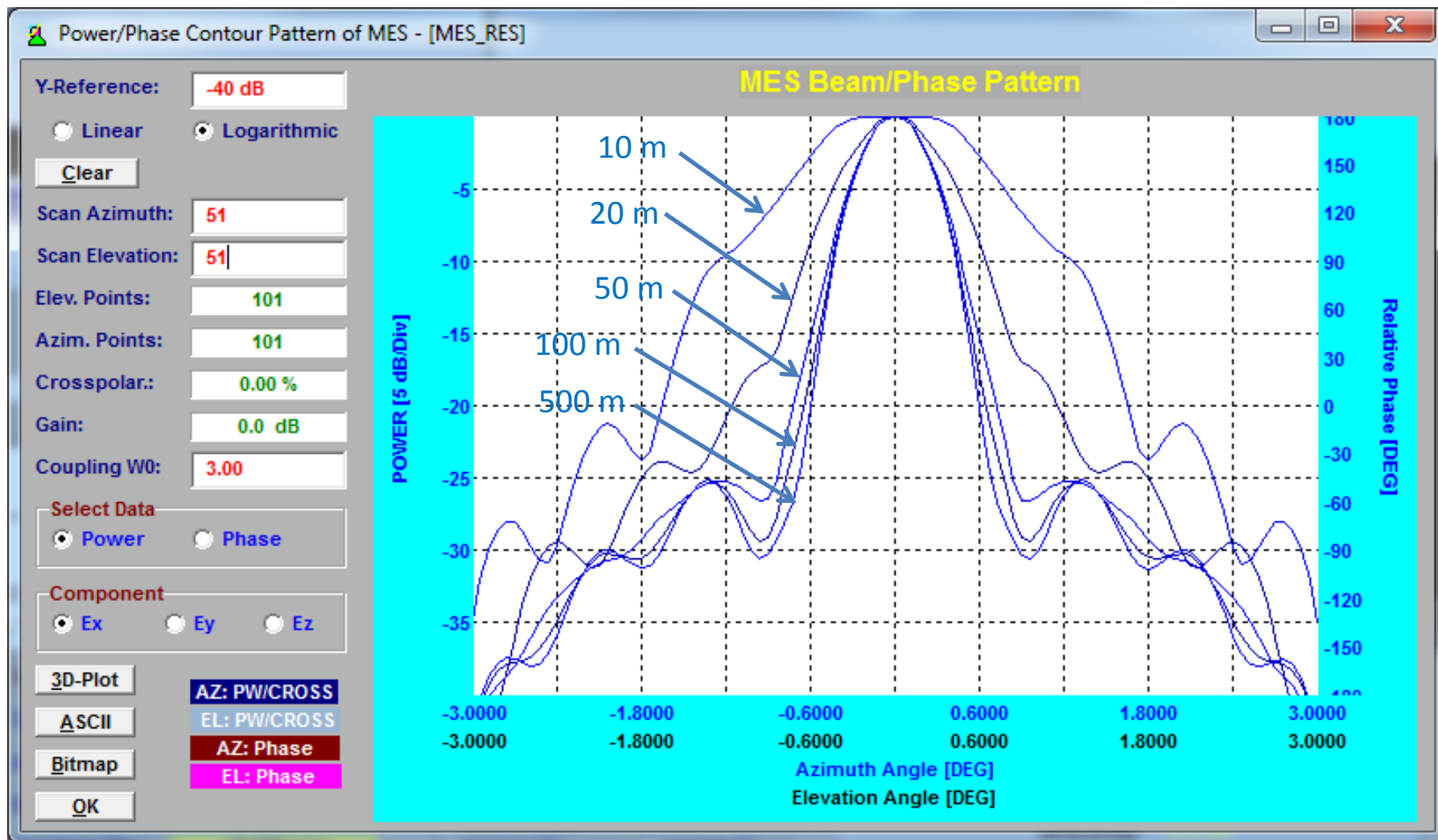


## Transmitter calibration issues:

1. Monitoring of output power, detector calibration
2. Power attenuation for dynamic range extension (17 dB)
3. Calibration of optical losses (feedhorns and Cassegr.)

## Receiver calibration issues:

1. Suppression of spurious detection signals from ADC
2. Dicke switch as internal ambient temp. Reference
3. Determination of Gains and  $T_{sys}$  in DD and Radar Ch.
4. Determination of total receiver chain gain
5. Correction of optical losses



Antenna far field can be assumed for distances  $>100$  m



# Spherical Reflector Calibration Results



Metal ball diameter: 48 mm  
 Reflector altitude: approx. 140 m  
 Reflector distance from radar: 960 m  
 Atmospheric attenuation: -0.6 dB  
 (path length 1900 m)

Expected power ratio  $P_r/P_t$ : -126.5 dB

Measured power ratio: -127.5  
 Corrected for attenuation: -126.9 dB

Deviation from theoretical value: 0.4 dB!



**Excellent Internal Radar Calibration!!**

